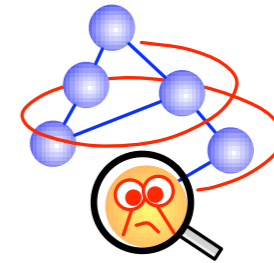
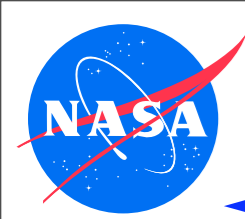


JavaPathfinder Tutorial

02/2010



Peter C. Mehlitz
SGT / NASA Ames Research Center
<Peter.C.Mehlitz@nasa.gov>



Objectives and Roadmap



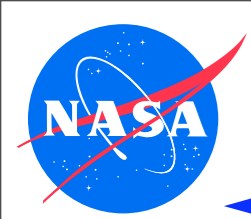
◆ Objectives

- get basic understanding of what JPF is
- learn by example what (current) JPF can be used for
- learn what it takes to install, configure and run JPF
- learn how JPF can be extended

learn
↓
use
↓
extend

◆ Roadmap

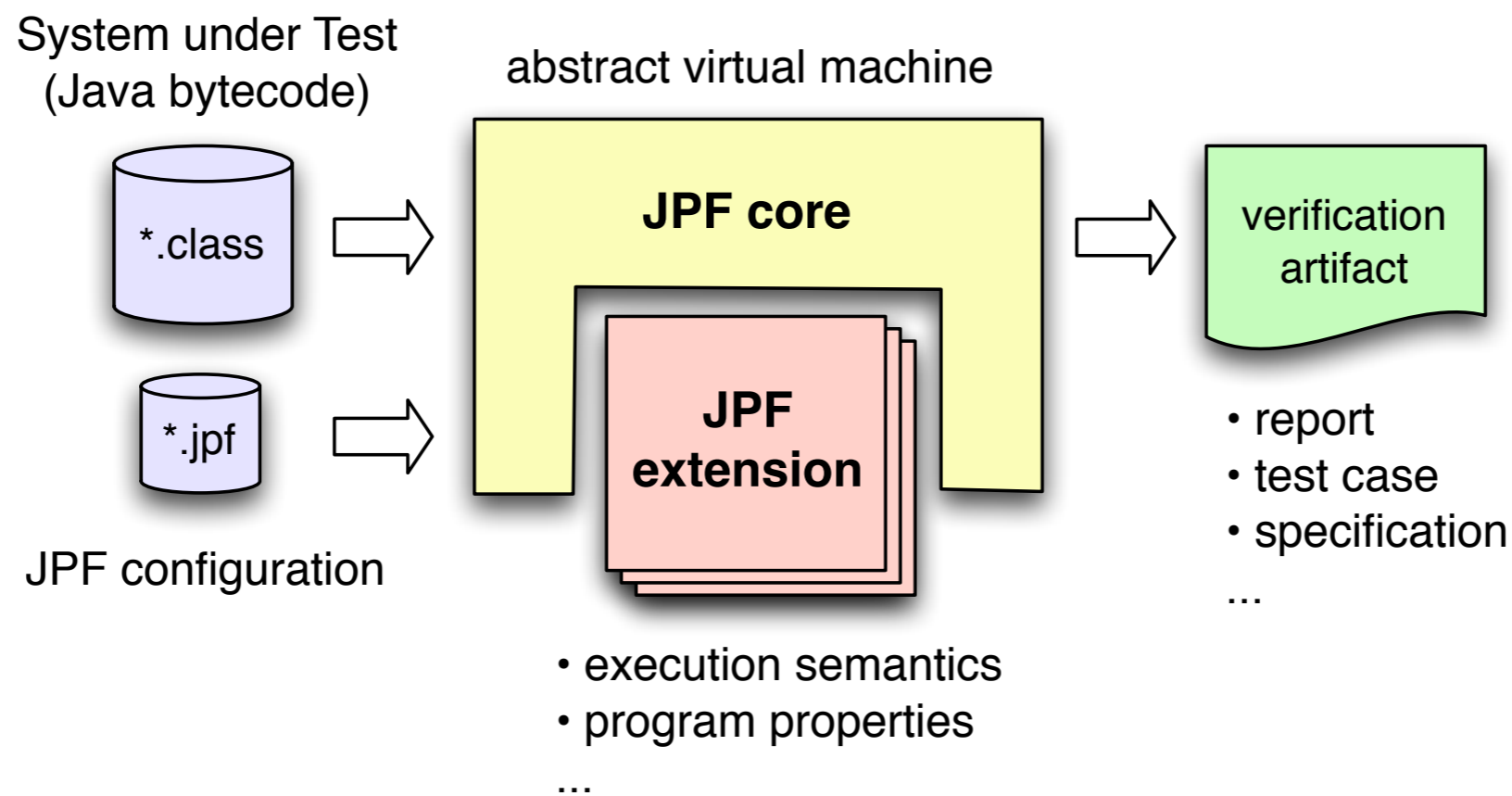
- | | |
|--|------|
| (1) Introduction | 1.0h |
| (2) Application Examples | 2.0h |
| (3) Installation, Configuration and Invocation | 1.0h |
| (4) Extension Mechanisms | 1.5h |
| (5) Discussion | |



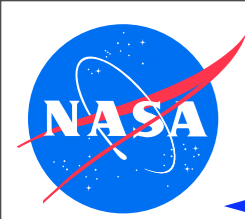
Introduction - What Is JPF?



- ◆ surprisingly hard to summarize - can be used for many things
- ◆ extensible virtual machine framework for Java bytecode verification: workbench to efficiently implement all kinds of verification tools



- ◆ typical use cases:
 - software model checking (deadlock & race detection)
 - deep inspection (numeric analysis, invalid access)
 - test case generation (symbolic execution)

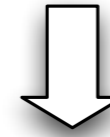


Example - What has JPF been used for ?



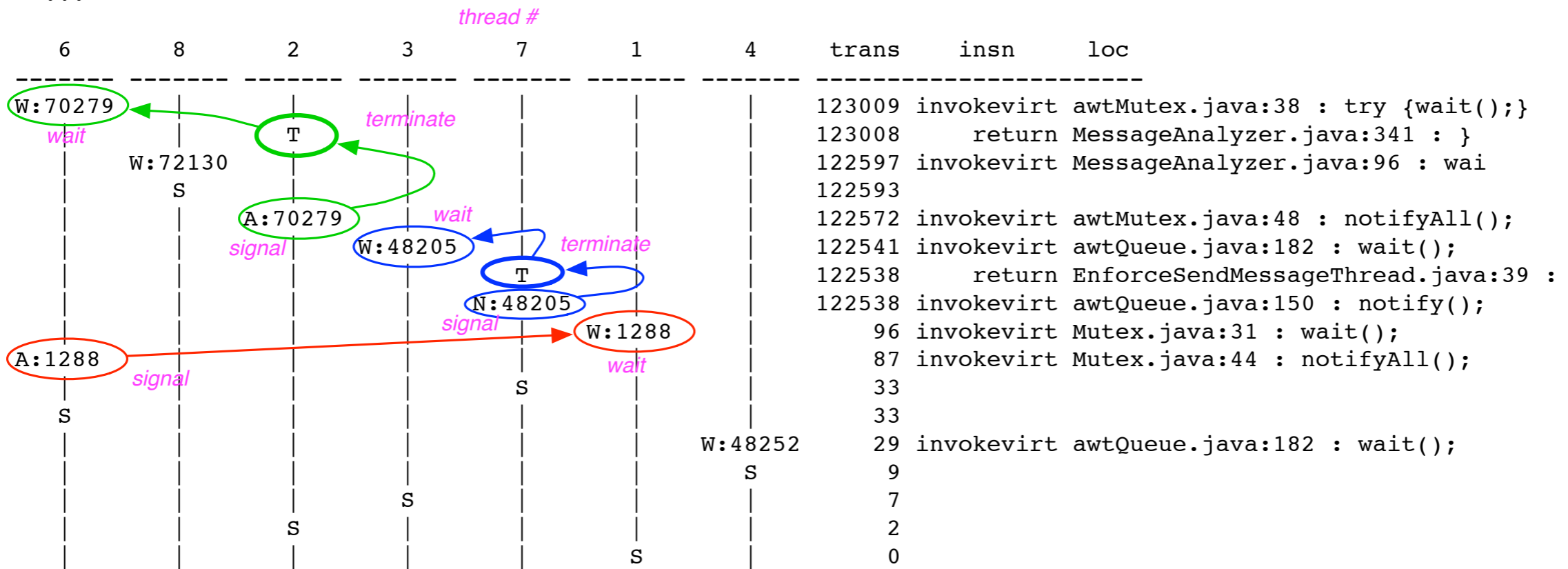
Objective: reproduce - *and analyze* - spurious deadlock in large web application

required stubbing, trace file >70MB, would have taken months to analyze manually



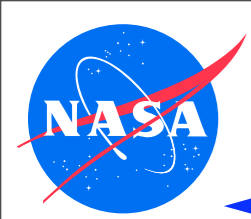
3 pairs of *missed signals* in set of 18 threads
missed signal = thread A signals before thread B waits
→ B is blocked on "lost" signal

```
===== error #1
deadlock encountered:
  thread index=0,name=main,status=TERMINATED
  thread index=1,name=Thread-0,status=WAITING
  thread index=2,name=Thread-1,status=TERMINATED
  thread index=3,name=Thread-2,status=WAITING
  ...
```



```
===== statistics
elapsed time:      3:53:23
states:           new=123010, visited=235893, backtracked=357879, end=81378
search:           maxDepth=1023, constraints=0
choice generators: thread=94664, data=0
heap:             gc=599818, new=7687542, free=12860670
instructions:     276556150
max memory:       9838MB
```

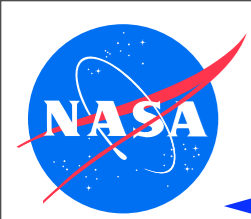
just one success story
for the type of deep
defects targeted by JPF



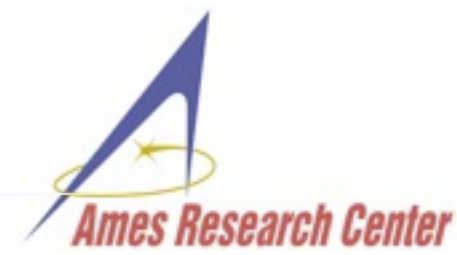
Who is using JPF ?



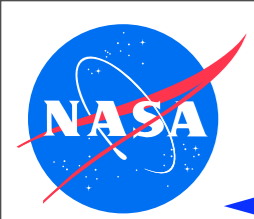
- ◆ major user group is academic research - collaborations with >20 universities worldwide (uiuc.edu, unl.edu, byu.edu, umn.edu, Stellenbosch Za, Waterloo Ca, AIST Jp, Charles University Prague Cz, ..)
- ◆ companies not so outspoken (exception Fujitsu - see press releases, e.g. <http://www.fujitsu.com/global/news/pr/archives/month/2010/20100112-02.html>) , but used by several Fortune 500 companies
- ◆ lots of (mostly) anonymous and private users (~1000 hits/day on website, ~10 downloads/day, ~60 read transactions/day, initially 6000 downloads/month)
- ◆ many uses inside NASA, but mostly model verification at Ames Research Center



History



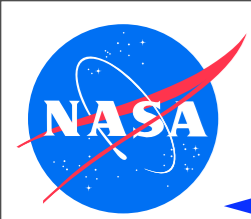
- ◆ not a new project: around since 10 years and continuously developed:
 - 1999 - project started as front end for Spin model checker
 - 2000 - reimplementations as concrete virtual machine for software model checking (concurrency defects)
 - 2003 - introduction of extension interfaces
 - 2005 - open sourced on Sourceforge
 - 2008 - participation in Google Summer of Code
 - 2009 - moved to own server, hosting extension projects and Wiki



Awards



- ◆ widely recognized, awards for JPF in general and for related work, team and individuals
 - 2002 - ACM Sigsoft Distinguished Paper award
 - 2003 - “Turning Goals into Reality” (TGIR) Engineering Innovation Award from the Office of AeroSpace Technology
 - 2004, 2005 - Ames Contractor Council Awards
 - 2007 - IBM's Haifa Verification Conference (HVC) award
 - 2009 - “Outstanding Technology Development” award of the Federal Laboratory Consortium for Technology Transfer (FLC)



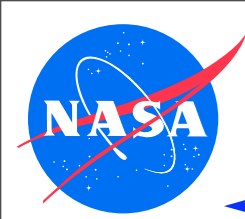
Caveat emptor - Costs of JPF application



- ◆ you need to learn
 - JPF is not a lightweight tool
 - flexibility has its price - configuration can be intimidating
 - might require extension for your SUT (properties, libraries)

- ◆ you will encounter unimplemented/missing parts (e.g. `UnsatisfiedLinkError`)
 - usually easy to implement
 - exception: state-relevant native libraries (`java.io`, `java.net`)
 - can be either modeled or stubbed

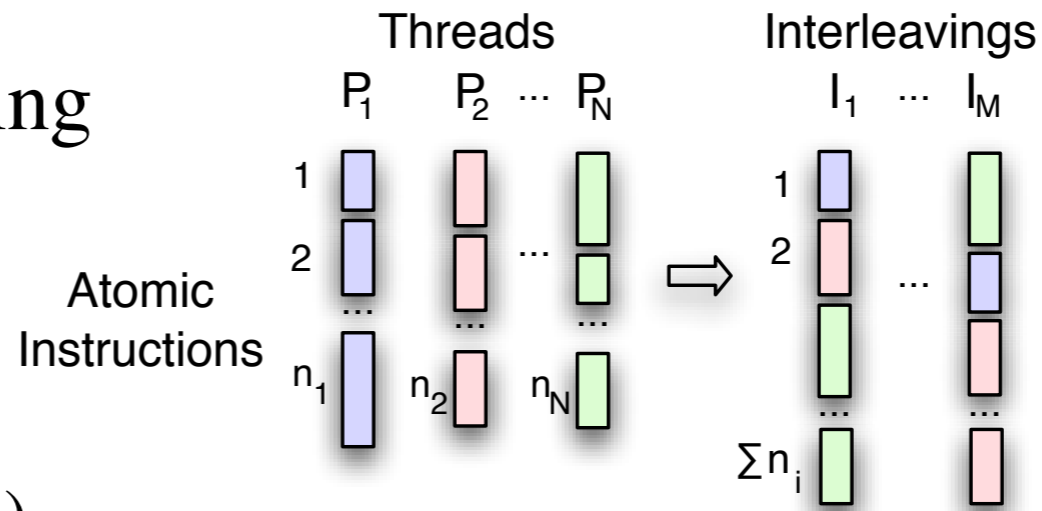
- ◆ you need suitable test drivers for concrete inspection & SMC



JPF's Challenges



- ◆ **theoretical:** model checking
scalability
⇒ optimization,
adaptation (config),
research (collaboration)



$$M = \frac{(\sum_{i=1}^N n_i)!}{\prod_{i=1}^N (n_i!)}$$

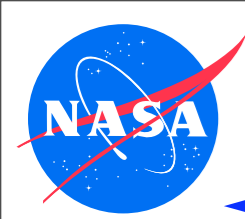
- ◆ **technical:**

- Java VM + libraries HUGE
a lot of ground to cover
⇒ reuse (libs, where possible)
- JPF is research platform *and* production tool at the same time
⇒ open sourcing (but no free lunch)

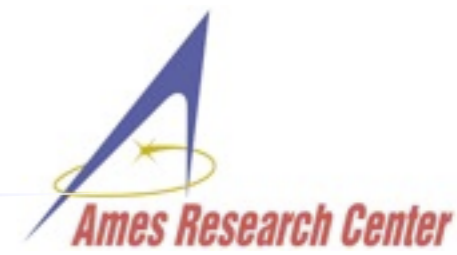
Java	files	loc	MB
OpenJDK	12,000	3.10E+06	118
JPF	1,600	2.04E+05	6

- ◆ **organizational:**

- small inhouse developer team
⇒ relies on external collaboration



Where to learn more - the JPF-Wiki



<http://babelfish.arc.nasa.gov/trac/jpf>

- public read access
- edit for account holders (also non-NASA)

bug tracking

- Trac ticket system

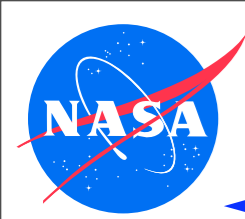
The screenshot shows the JPF Wiki website. The browser address bar contains <http://babelfish.arc.nasa.gov/trac/jpf/wiki>. The page header includes the JPF logo and the tagline "the swiss army knife of Java™ verification". A navigation bar contains buttons for "JPF-Wiki", "Timeline", "Roadmap", "View Tickets", "New Ticket", "Search", "Admin", and "Blog". Below the navigation bar is a "Latest JPF News" section with a table of recent updates. A "Welcome to the JPF Wiki" section provides introductory text. On the right side, a "JPFWiki - Welcome Page" navigation menu lists various sections like "Introduction...", "Installing JPF...", "User Guide...", "Developer Guide...", "Projects...", "Change(B)log", "About...", "Papers", "FAQ", "Playground", and "Table of Context".

project blog

- announcements
- important changes

hierarchical navigation menu

- intro
- installation
- user docu
- developer docu
- **extension projects**



Introduction: Key Points

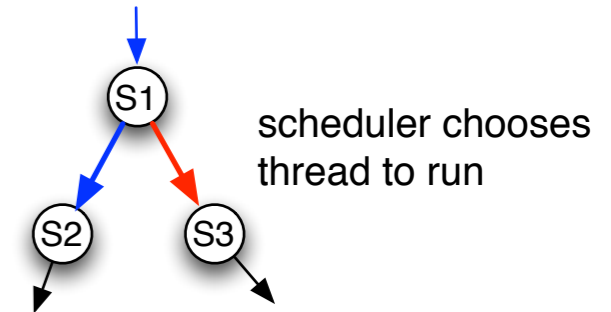
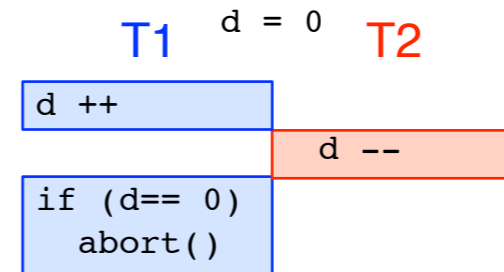


- ◆ JPF is research platform *and* production tool (basis)
- ◆ JPF is designed for extensibility
- ◆ JPF is open source
- ◆ JPF is an ongoing collaborative development project
- ◆ JPF cannot find all bugs
 - but as of today -
 - some of the most expensive bugs only JPF can find
- ◆ JPF is moderately sized system (~200ksloc core + extensions)
- ◆ JPF represents >20 man year development effort
- ◆ JPF is pure Java application (platform independent)

goal is to show gamut of possible applications, not detailed defect understanding

◆ software model checking (SMC) of production code

- data acquisition (random, user input)
- concurrency (deadlock, races)



◆ deep inspection of production code

- property annotations (Const, PbC,..)
- numeric verification (overflow, cancellation)

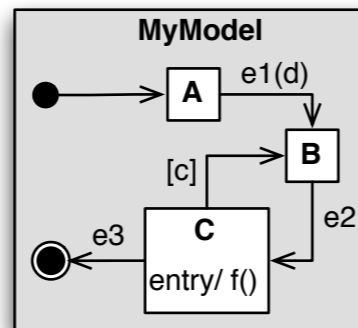
```
@Const
int dontChangeMe() {...}
```

```
double x = (y - z) * c
```

numeric error of x?

◆ model verification

- UML statecharts



does model work?

◆ test case generation

◆ verification of distributed application

JPF unaware programs

runs on any JVM



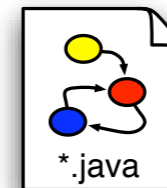
JPF enabled programs

"sweet spot"



JPF dependent programs

runs only under JPF



constraints

runtime costs

- order of magnitude slower
- state storage memory

standard library support

- java.net, javax.swing, .. (needs abstraction models)

functional property impl. costs

- listeners, MJI knowledge

restricted choice types

- scheduling sequences
- java.util.Random

annotate program

- requirements
- sequences (UML)
- contracts (PbC)
- tests
- ...

analyze program

- symbolic exec → test data
- thread safety / races

restricted application models

- UML statemachines
- does not run w/o JPF libraries

initial domain impl. costs

- domain libs can be tricky

benefits

non-functional properties

- unhandled exceptions (incl. AssertionError)
- deadlocks
- races

improved inspection

- coverage statistics
- exact object counts
- execution costs

low modeling costs

- statemachine w/o layout hassle,..

functional (domain) properties

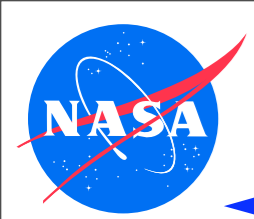
- built-in into JPF libraries

flexible state space

- domain specific choices (e.g. UML "enabling events")

runtime costs & library support

- usually not a problem, domain libs can control state space



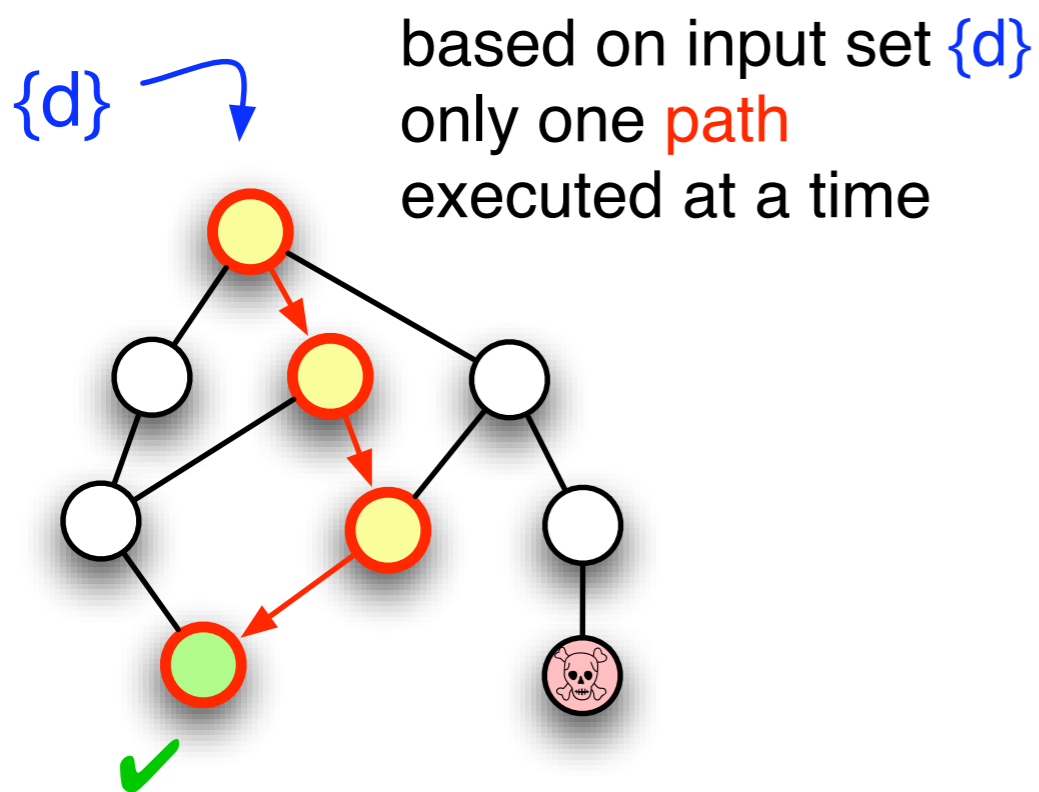
Examples: Software Model Checking



- ◆ focus is on *production code*, i.e. SUT applications are not specifically written for JPF
- ◆ might include abstracted/modeled libraries, but no modified SUT behavior
- ◆ objective: check execution paths that are hard or impossible to test reliably (scheduling sequences, large input spaces, mix between both)
- ◆ classic application: detect concurrency defects

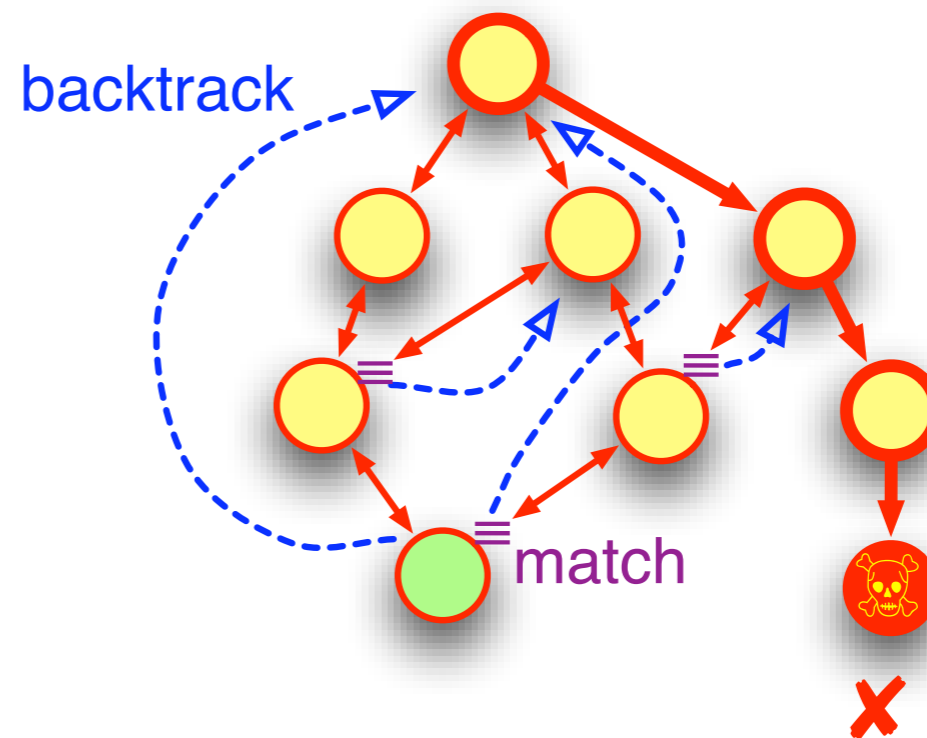
- ◆ SMC is a rigorous formal method
- ◆ SMC does not suffer from false positives (like static analysis)
- ◆ SMC provides traces (execution history) when it finds a defect

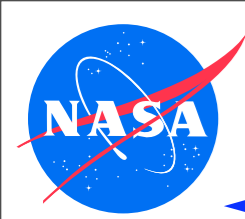
testing:



model checking:

all program state are explored
 until none left or defect found





Model Checking vs. Debugging



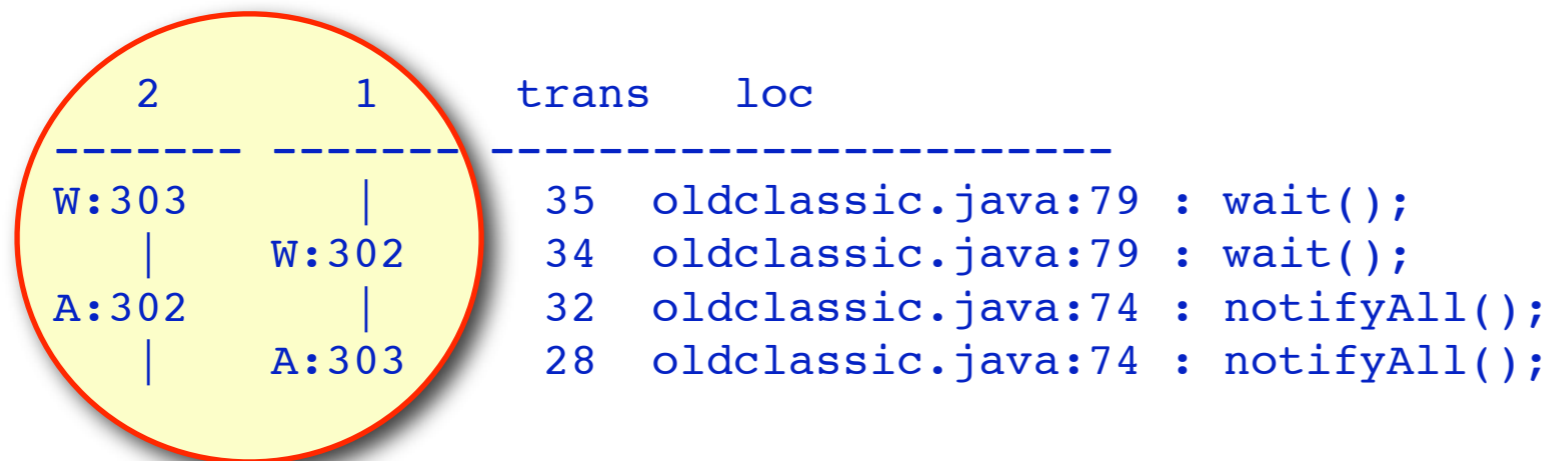
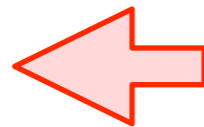
- ◆ JPF automatically *finds* defects to debug
- ◆ program traces - JPF *remembers* whole execution history that lead to defect
- ◆ automatic trace analysis capability *explains* defects

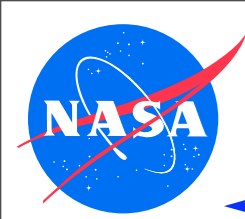
```

deadlock encountered:
  thread index=1,name=Thread-0,status=WAITING,...
  thread index=2,name=Thread-1,status=WAITING,...
  ...
----- transition #32 thread: 2
oldclassic.java:127 : event1.signal_event();
oldclassic.java:71  : count = (count + 1) % 3;
oldclassic.java:74  : notifyAll();
oldclassic.java:75  : }
oldclassic.java:129 : if (count == event2.count)
----- transition #33 thread: 1
oldclassic.java:103 : event1.wait_for_event();
oldclassic.java:79  : wait();
  ...

```

Trace Analysis





Example 1: Nondeterministic Data (1)



◆ Source

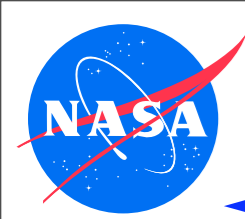
```
..   public static void main (String[] args) {  
..   ...  
7:   Random random = new Random(42);      // (1)  
8:   int a = random.nextInt(2);          // (2)  
..   ...  
13:  int b = random.nextInt(3);          // (3)  
..   ...  
16:  int c = a/(b+a -2);                  // (4)  
..   ...  
..   }
```

◆ Config

```
cg.enumerate_random = true
```

◆ Output

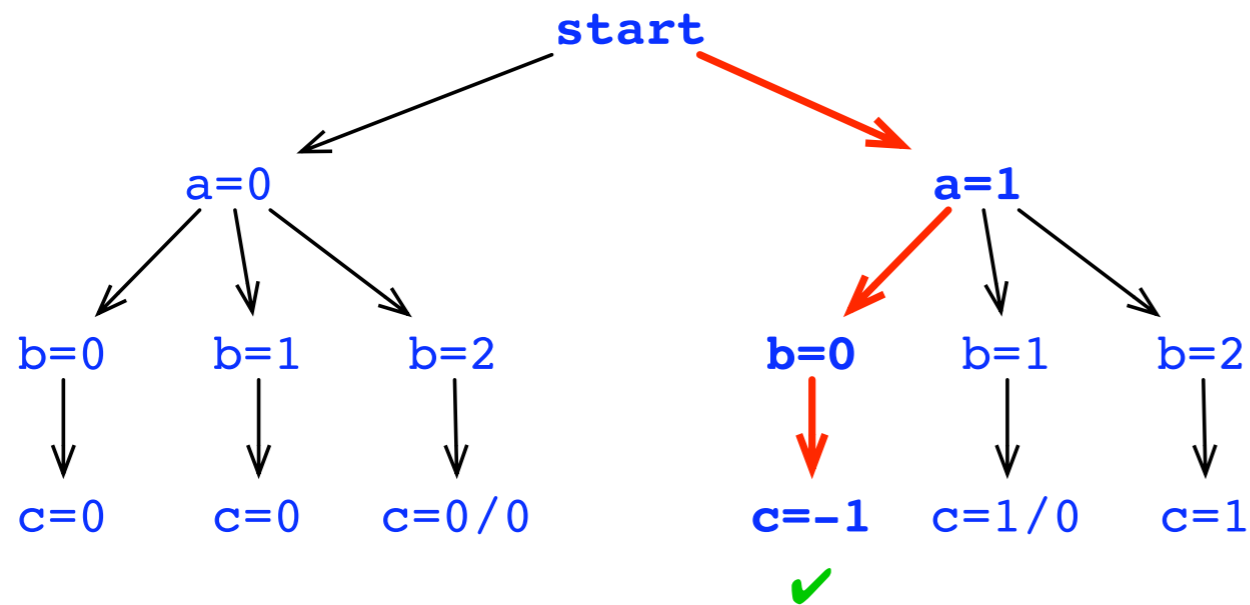
```
...  
===== search started: 2/10/10 6:08 PM  
computing c = a/(b+a - 2)..  
a=0  
  b=0      ,a=0  
=> c=0     ,a=0,b=0  
  b=1      ,a=0  
=> c=0     ,a=0,b=1  
  b=2      ,a=0  
  
===== error #1  
gov.nasa.jpj.jvm.NoUncaughtExceptionsProperty  
java.lang.ArithmeticException: division by zero  
    at Rand.main(Rand.java:16)
```



Example 1: Nondeterministic Data (2)



◆ Testing only covers one execution



① `Random random = new Random()`

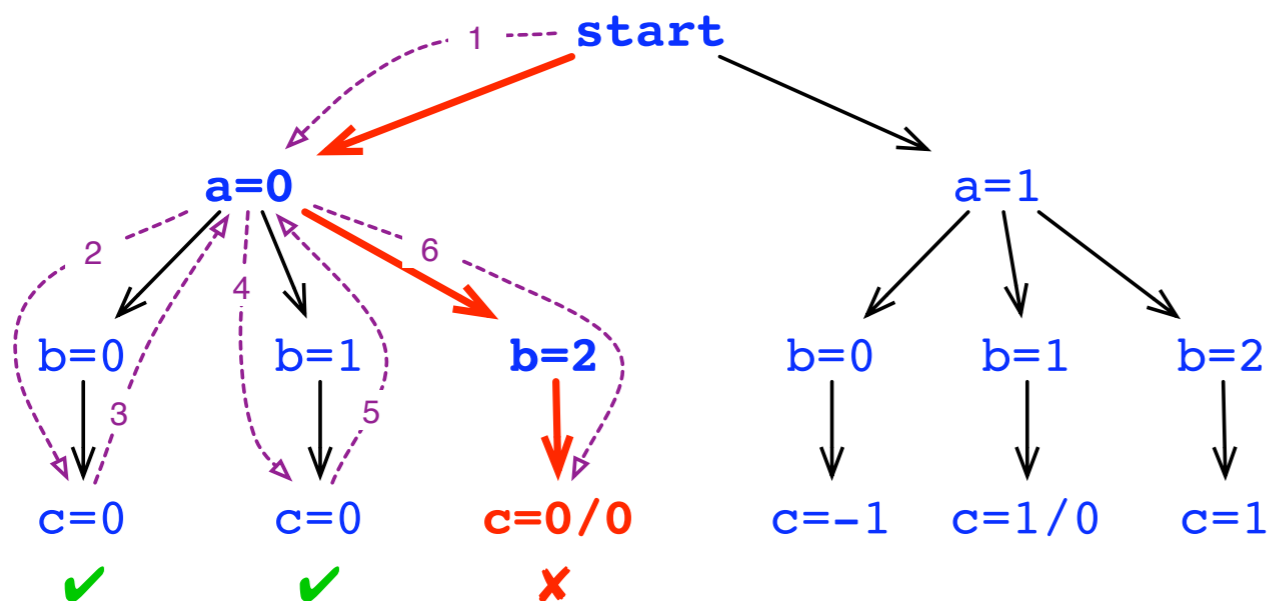
② `int a = random.nextInt(2)`

③ `int b = random.nextInt(3)`

④ `int c = a/(b+a -2)`

```
>java Rand
a=1
b=0
c=-1
```

◆ Model checking (theoretically) covers all executions

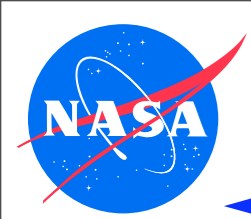


```
>jpf +cg.enumerate_random=true
```

```
  Rand
```

```
a=0
b=0
c=0
b=1
c=0
b=2
```

```
ERROR: ArithmeticException
```



Example 2: Data Race (1)



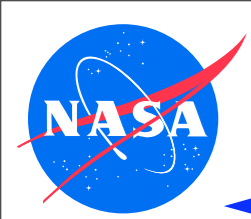
◆ Source

```
int d = 42;

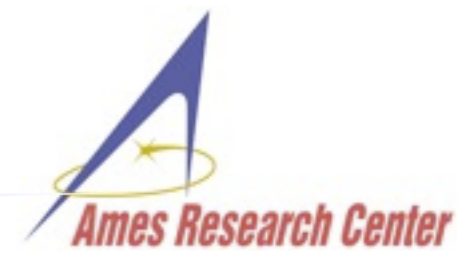
public void run () {
    doSomething(1001);           // (1)
    d = 0;                       // (2)
}

public static void main (String[] args){
    Racer racer = new Racer();
    Thread t = new Thread(racer);
    t.start();

    doSomething(1000);           // (3)
    int c = 420 / racer.d;       // (4)
    System.out.println(c);
}
```



Example 2: Data Race (1)



◆ Source

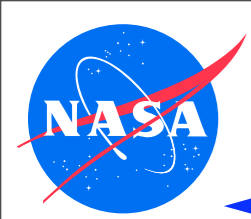
```
int d = 42;

public void run () {
    doSomething(1001);           // (1)
    d = 0;                       // (2)
}

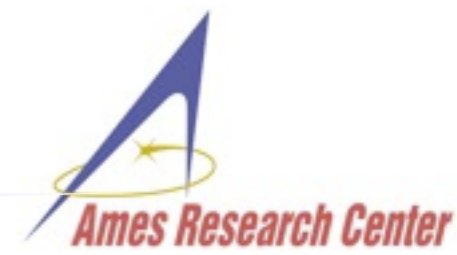
public static void main (String[] args){
    Racer racer = new Racer();
    Thread t = new Thread(racer);
    t.start();

    doSomething(1000);           // (3)
    int c = 420 / racer.d;       // (4)
    System.out.println(c);
}
```

data race



Example 2: Data Race (2)

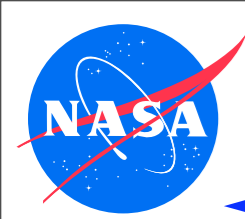


◆ Config

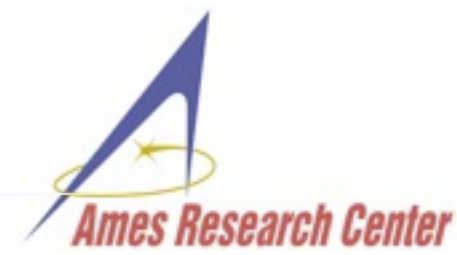
```
listener = gov.nasa.jpff.listener.PreciseRaceDetector  
report.console.property_violation = error,trace
```

◆ Output

```
...  
===== search started: 2/10/10 6:32 PM  
10  
10  
===== error #1  
gov.nasa.jpff.listener.PreciseRaceDetector  
race for field Racer@287.d  
  main at Racer.main(Racer.java:16)  
           "int c = 420 / racer.d;           " : getfield  
  Thread-0 at Racer.run(Racer.java:7)  
           "d = 0;                           " : putfield  
===== trace #1  
----- transition #0 thread: 0  
gov.nasa.jpff.jvm.choice.ThreadChoiceFromSet {>main}  
  [2843 insn w/o sources]  
  ...  
  Racer.java:16           : int c = 420 / racer.d;  
----- transition #4 thread: 1  
gov.nasa.jpff.jvm.choice.ThreadChoiceFromSet {main,>Thread-0}  
  ...  
  Racer.java:7           : d = 0;  
----- transition #5 thread: 0  
gov.nasa.jpff.jvm.choice.ThreadChoiceFromSet {>main,Thread-0}  
  Racer.java:16           : int c = 420 / racer.d;
```



Example 3: Deadlock (1)



```
class FirstTask extends Thread {
    Event event1, event2;
    int    count = 0;
    ...
    public void run () {
        count = event1.count;

        while (true) {
            if (count == event1.count) {
                event1.wait_for_event();
            }

            count = event1.count;
            event2.signal_event();
        }
    }
}
```

```
class SecondTask extends Thread {
    Event event1, event2;
    int    count = 0;
    ...
    public void run () {
        count = event2.count;

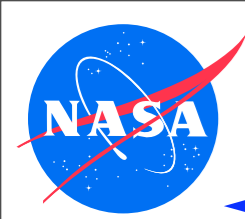
        while (true) {
            event1.signal_event();

            if (count == event2.count) {
                event2.wait_for_event();
            }

            count = event2.count;
        }
    }
}
```

```
class Event {
    int count = 0;

    public synchronized void signal_event () {
        count++;  notifyAll();
    }
    public synchronized void wait_for_event () {
        .. wait(); ..
    }
}
```



Example 3: Deadlock (2)



- ◆ Report - shows what happened, but not easily why

```
JavaPathfinder v5.x - (C) RIACS/NASA Ames Research Center
```

```
===== system under test  
application: oldclassic.java
```

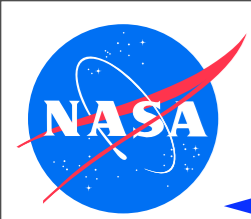
```
===== search started: 2/11/10 11:10 AM
```

```
1  
  2  
1  
  2  
1  
...
```

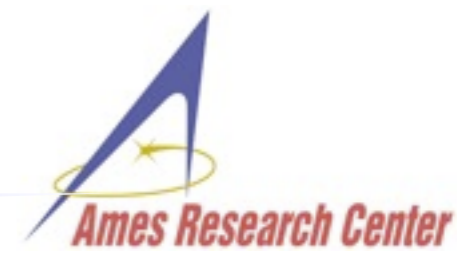
```
===== error #1
```

```
gov.nasa.jpf.jvm.NotDeadlockedProperty  
deadlock encountered:
```

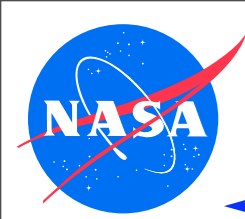
```
  thread index=0,name=main,status=TERMINATED,this=null,target=null,...  
  thread index=1,name=Thread-0,status=WAITING,this=FirstTask@295,lockCount=1,...  
  thread index=2,name=Thread-1,status=WAITING,this=SecondTask@322,lockCount=1,...  
...
```



Example 3: Deadlock (3)



```
...
===== trace #1
----- transition #0 thread: 0
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>main}
  [2843 insn w/o sources]
  oldclassic.java:47      : Event      new_event1 = new Event();
...
----- transition #29 thread: 1
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-0,Thread-1}
  oldclassic.java:102    : if (count == event1.count) {
  oldclassic.java:103    : event1.wait_for_event();
----- transition #30 thread: 2
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {Thread-0,>Thread-1}
  oldclassic.java:129    : if (count == event2.count) {
  oldclassic.java:133    : count = event2.count;
...
  oldclassic.java:126    : System.out.println(" 2");
  oldclassic.java:127    : event1.signal_event();
...
  oldclassic.java:71     : count = (count + 1) % 3;
  oldclassic.java:74     : notifyAll();
  oldclassic.java:75     : }
  oldclassic.java:129    : if (count == event2.count) {
----- transition #33 thread: 1
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-0,Thread-1}
  oldclassic.java:103    : event1.wait_for_event();
  oldclassic.java:79     : wait();
----- transition #34 thread: 2
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-1}
  oldclassic.java:129    : if (count == event2.count) {
  oldclassic.java:130    : event2.wait_for_event();
  oldclassic.java:79     : wait();
```

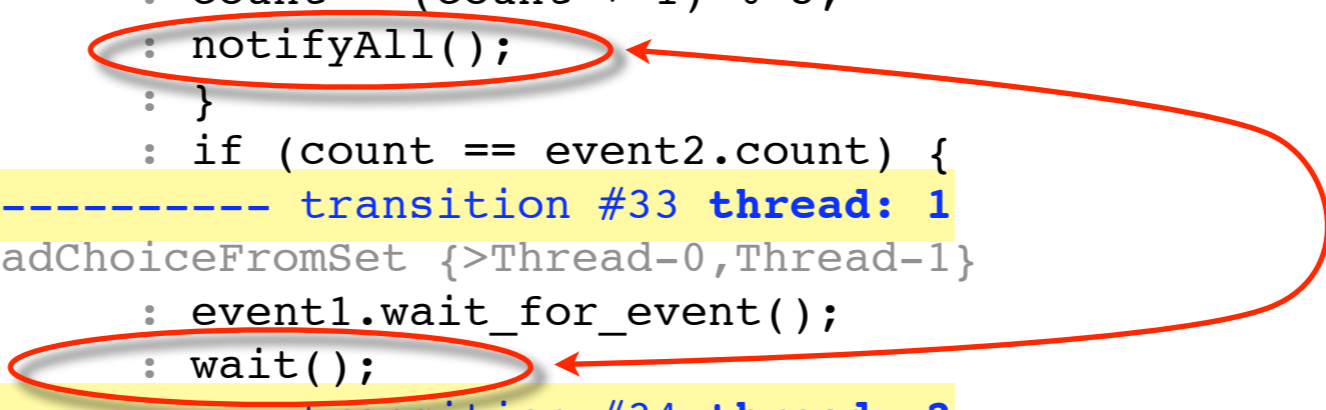
Example 3: Deadlock (3)



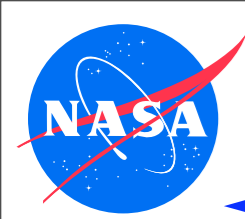
```

...
===== trace #1
----- transition #0 thread: 0
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>main}
  [2843 insn w/o sources]
  oldclassic.java:47      : Event      new_event1 = new Event();
...
----- transition #29 thread: 1
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-0,Thread-1}
  oldclassic.java:102    : if (count == event1.count) {
  oldclassic.java:103    : event1.wait_for_event();
----- transition #30 thread: 2
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {Thread-0,>Thread-1}
  oldclassic.java:129    : if (count == event2.count) {
  oldclassic.java:133    : count = event2.count;
...
  oldclassic.java:126    : System.out.println(" 2");
  oldclassic.java:127    : event1.signal_event();
...
  oldclassic.java:71     : count = (count + 1) % 3;
  oldclassic.java:74     : notifyAll();
  oldclassic.java:75     : }
  oldclassic.java:129    : if (count == event2.count) {
----- transition #33 thread: 1
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-0,Thread-1}
  oldclassic.java:103    : event1.wait_for_event();
  oldclassic.java:79     : wait();
----- transition #34 thread: 2
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {>Thread-1}
  oldclassic.java:129    : if (count == event2.count) {
  oldclassic.java:130    : event2.wait_for_event();
  oldclassic.java:79     : wait();

```



missed
signal



Example 3: Deadlock (4)



```
report.console.property_violation = error, snapshot
listener = .listener.DeadlockAnalyzer
```

```
==== error #1
```

```
gov.nasa.jpf.jvm.NotDeadlockedProperty
deadlock encountered:
```

```
...
```

```
==== snapshot #1
```

```
thread index=1,name=Thread-0,status=WAITING,this=FirstTask@295 ...
```

```
waiting on: Event@290
```

```
call stack:
```

```
at Event.wait_for_event(oldclassic.java:79)
at FirstTask.run(oldclassic.java:103)
```

```
thread index=2,name=Thread-1,status=WAITING,this=SecondTask@322 ...
```

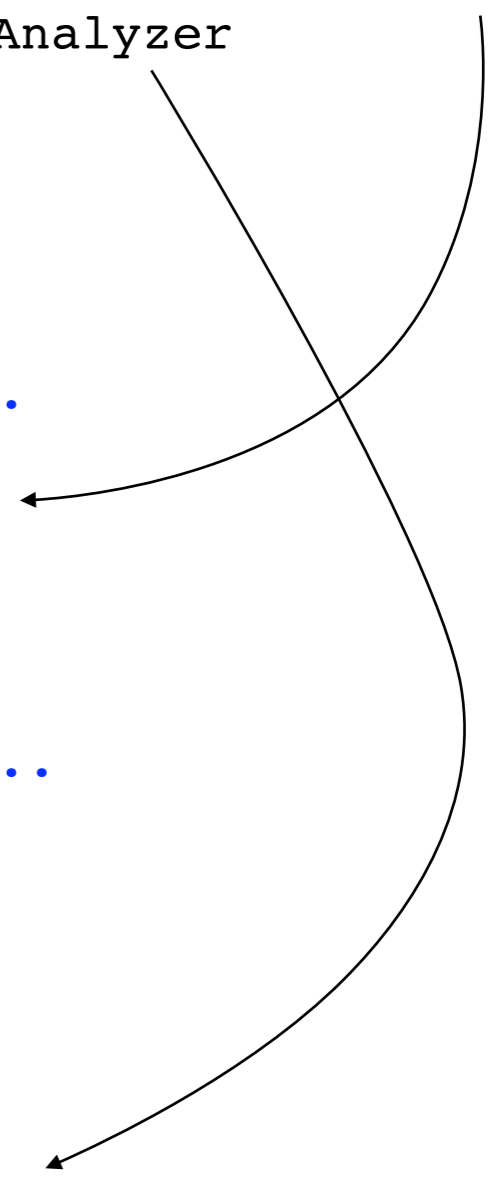
```
waiting on: Event@291
```

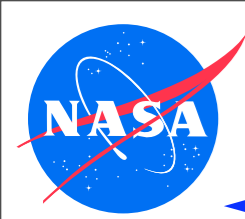
```
call stack:
```

```
at Event.wait_for_event(oldclassic.java:79)
at SecondTask.run(oldclassic.java:130)
```

```
==== thread ops #1
```

2	1	trans	insn	loc
W:291		37	invokevirt	oldclassic.java:79 : wait();
	W:290	36	invokevirt	oldclassic.java:79 : wait();
A:290		35	invokevirt	oldclassic.java:74 : notifyAll();
	A:291	28	invokevirt	oldclassic.java:74 : notifyAll();
S		1		
	S	0		





Example 4: User Input Model Checking (1)



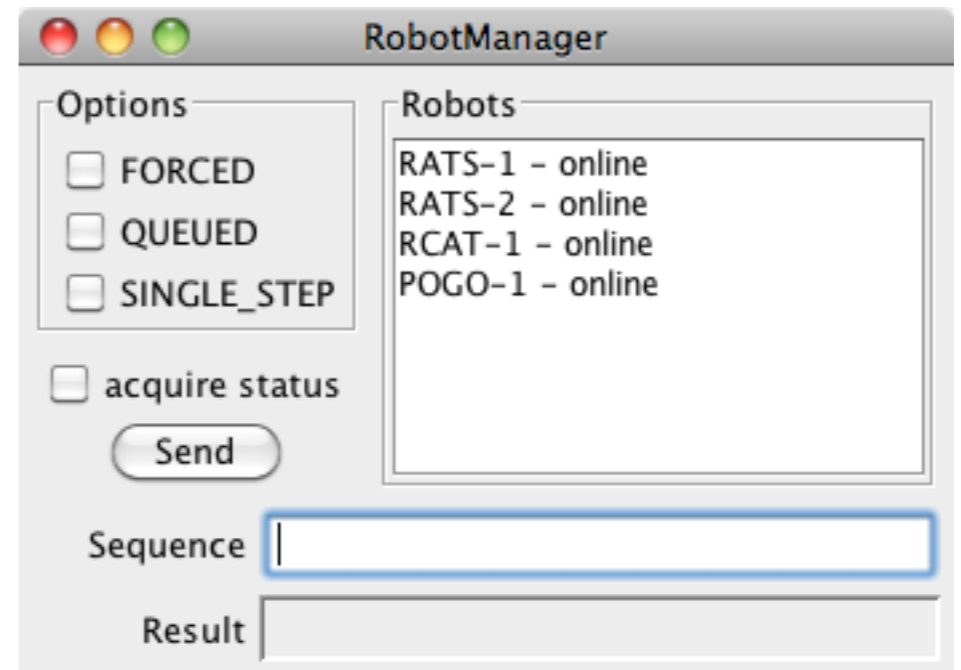
- specify user input in event script with alternatives

```
// enter command sequence
$Sequence:input.setText("turn")
```

```
// try all Options combinations
ANY { $<FORCED|QUEUED|SINGLE_STEP>.doClick() }
ANY { $<FORCED|QUEUED|SINGLE_STEP>.doClick() }
ANY { $<FORCED|QUEUED|SINGLE_STEP>.doClick() }
```

```
// select robot
ANY { $Robots:list.setSelectedIndex(0|1|2|3) }
```

```
// send sequence
$Send.doClick()
```



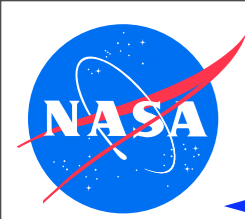
```
input.setText(..)
FORCED.doClick()
FORCED.doClick()
FORCED.doClick()
list.setSelectedIndex(0)
Send.doClick()
```

```
input.setText(..)
QUEUED.doClick()
...
```

generated event sequences

...

```
input.setText(..)
SINGLE_STEP.doClick()
SINGLE_STEP.doClick()
SINGLE_STEP.doClick()
list.setSelectedIndex(3)
Send.doClick()
```



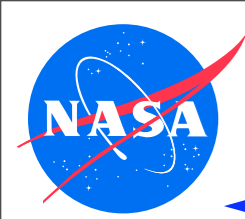
Example 4: User Input Model Checking (2)



- ◆ Finds input combination that causes exception in user code:

```
=====  
gov.nasa.jpjvm.NoUncaughtExceptionsProperty  
java.lang.AssertionError: POGOs cannot force queued sequences  
    at POGO.processSequence(RobotManager.java:92)  
    at RobotManager.sendSequence(RobotManager.java:264)  
    ...
```

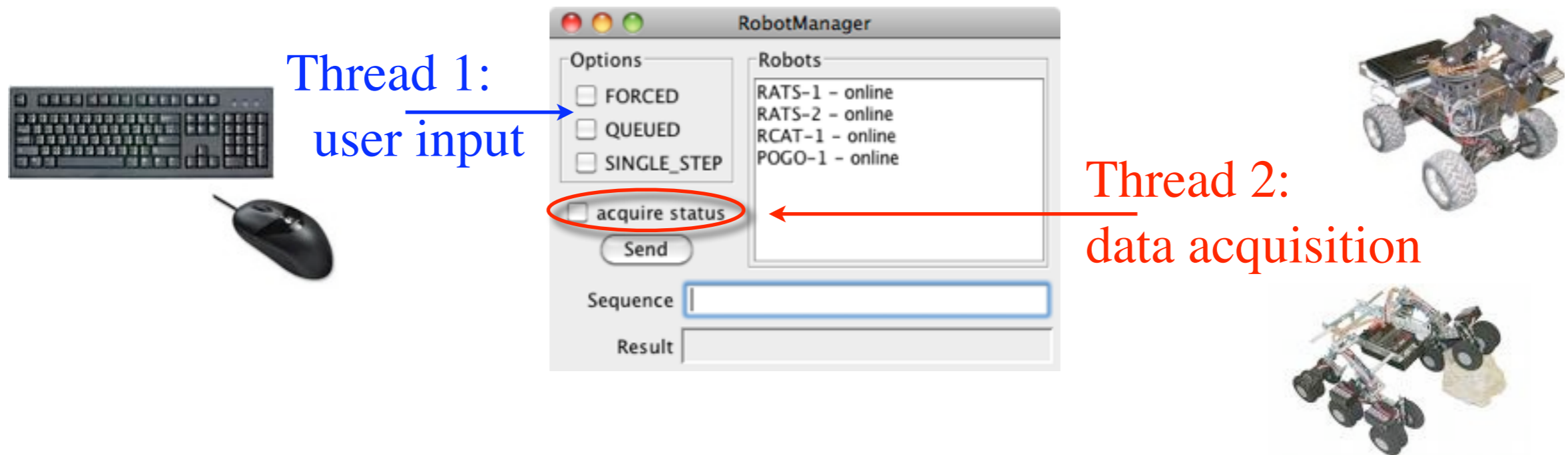
```
=====  
0: gov.nasa.jpjvm.UIActionSingleChoice[.. >$Sequence:input.setText("turn")]  
1: gov.nasa.jpjvm.UIActionFromSet[.. >$FORCED.doClick(),  
    $QUEUED.doClick(),  
    $SINGLE_STEP.doClick()]  
2: gov.nasa.jpjvm.UIActionFromSet[.. $FORCED.doClick(),  
    >$QUEUED.doClick(),  
    $SINGLE_STEP.doClick()]  
3: gov.nasa.jpjvm.UIActionFromSet[.. $FORCED.doClick(),  
    $QUEUED.doClick(),  
    >$SINGLE_STEP.doClick()]  
4: gov.nasa.jpjvm.UIActionFromSet[.. $Robots:list.setSelectedIndex(0),  
    $Robots:list.setSelectedIndex(1),  
    $Robots:list.setSelectedIndex(2),  
    >$Robots:list.setSelectedIndex(3)]  
5: gov.nasa.jpjvm.UIActionSingleChoice[.. >$Send.doClick()]
```

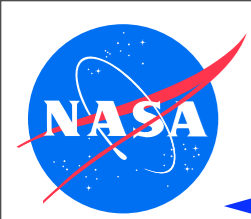


Example 5: Multithreaded GUI (1)



- ◆ extended GUI application that uses concurrent data acquisition
- ◆ thread structure not obvious because of large portions of framework / library code (swing)
- ◆ application logic mostly implemented as callback actions
- ◆ two overlaid non-determinisms: user input and scheduling sequence
- ◆ “impossible” to test





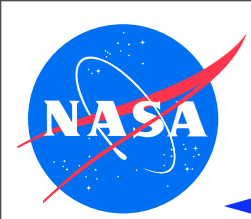
Example 5: Multithreaded GUI (2)



- ◆ JPF finds defect that is untestable, but..

general,
low level
defect

```
UIShell
Properties Report Test Output Verify Output Components Trace Script
JavaPathfinder v5.x - (C) RIACS/NASA Ames Research Center
===== system under test
application: RobotManager.java
===== search started: 2/17/10 10:03 AM
===== error #1
gov.nasa.jpf.jvm.NoUncaughtExceptionsProperty
java.lang.NullPointerException: calling 'processSequence(Ljava/lang/String;)Ljava/lang/String;' c
  at RobotManager.sendSequence(RobotManager.java:266)
  at RobotManagerView.sendSequence(RobotManager.java:538)
  at RobotManagerView$3.actionPerformed(RobotManager.java:339)
  at javax.swing.AbstractButton.fireActionPerformed(AbstractButton.java:113)
  at javax.swing.AbstractButton$Handler.actionPerformed(AbstractButton.java:41)
  at javax.swing.DefaultButtonModel.fireActionPerformed(DefaultButtonModel.java:387)
  at javax.swing.DefaultButtonModel.setPressed(DefaultButtonModel.java:242)
  at javax.swing.AbstractButton.doClick(AbstractButton.java:187)
  at java.awt.EventDispatchThread.run(EventDispatchThread.java:65)
===== snapshot #1
thread index=1,name=AWT-EventQueue-0,status=RUNNING,this=java.awt.EventDispatchThread@2595,priori
call stack:
  at RobotManager.sendSequence(RobotManager.java:266)
  at RobotManagerView.sendSequence(RobotManager.java:538)
  at RobotManagerView$3.actionPerformed(RobotManager.java:339)
  at javax.swing.AbstractButton.fireActionPerformed(AbstractButton.java:113)
  at javax.swing.AbstractButton$Handler.actionPerformed(AbstractButton.java:41)
  at javax.swing.DefaultButtonModel.fireActionPerformed(DefaultButtonModel.java:387)
  at javax.swing.DefaultButtonModel.setPressed(DefaultButtonModel.java:242)
  at javax.swing.AbstractButton.doClick(AbstractButton.java:187)
  at java.awt.EventDispatchThread.run(EventDispatchThread.java:65)
thread index=2,name=Thread-1,status=SLEEPING,this=RobotStatusAcquisitionThread@2635,priority=5,lo
call stack:
```



Example 5: Multithreaded GUI (3)



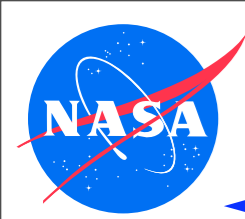
- ◆ trace too long to find out what causes it - needs more analysis

```

UIShell
Properties Report Test Output Verify Output Components Trace Script
RobotManager.java:257      : return onlineRobots.get(robotName);
RobotManager.java:537      : Robot robot = model.getOnlineRobot(selectedRobotName);
RobotManager.java:538      : String result = model.sendSequence(robot, sequence);
----- transition #169 thread: 2
gov.nasa.jpfc.jvm.choice.ThreadChoiceFromSet (>Thread-1,AWT-EventQueue-0)
RobotManager.java:245      : listModel.changed(robot);
RobotManager.java:184      : int idx = robots.indexOf(robot);
----- transition #170 thread: 2
gov.nasa.jpfc.jvm.choice.ThreadChoiceFromSet (>Thread-1,AWT-EventQueue-0)
RobotManager.java:184      : int idx = robots.indexOf(robot);
[23 insn w/o sources]
RobotManager.java:184      : int idx = robots.indexOf(robot);
RobotManager.java:185      : if (idx >= 0) {
RobotManager.java:186      :   fireContentsChanged(this, idx, idx);
[17 insn w/o sources]
RobotManager.java:188      : }
RobotManager.java:246      : }
RobotManager.java:151      : Thread.sleep(3000);
[3 insn w/o sources]
----- transition #171 thread: 1
gov.nasa.jpfc.jvm.choice.ThreadChoiceFromSet (>AWT-EventQueue-0,Thread-1)
RobotManager.java:538      : String result = model.sendSequence(robot, sequence);
RobotManager.java:266      : return robot.processSequence(sequence);
===== results
error #1: gov.nasa.jpfc.jvm.NoUncaughtExceptionsProperty "java.lang.NullPointerException: calling
===== statistics
elapsed time:      0:00:17
states:           new=8812, visited=8917, backtracked=17557, end=0
search:           maxDepth=836, constraints=0
choice generators: thread=8220, data=592
heap:             gc=18126, new=15942, free=11676
instructions:     870251
max memory:       84MB
loaded code:      classes=350, methods=4109
===== search finished: 2/17/10 10:03 AM

```

too deep
to understand



Example 5: Multithreaded GUI (4)



- ◆ generic trace analysis can help (e.g. hierarchical method execute/return log with MethodAnalyzer listener)
- ◆ still too time consuming in many cases

```
listener=.listener.MethodAnalyzer
method.include=*Robot*
...
```



thread 1

```
...
1: .....R RobotManager.isRobotOnline(..)Z, RobotManager@287
```

thread 2

```
...
2: ..X RobotManager.isRobotOnline(..)Z, RobotManager@287
```

```
1: .....X RobotManager.getOnlineRobot(..)LRobot;;, RobotManager@287
```

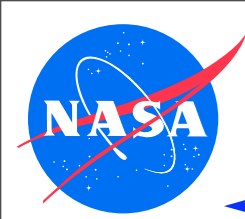
```
...
2: ..R RobotManager.isRobotOnline(..)Z, RobotManager@287
```

```
2: ..X RobotManager.setRobotOnline(LRobot;Z)V, RobotManager@287
```

```
...
1: .....R RobotManager.getOnlineRobot(..)LRobot;;, RobotManager@287
```

```
...
2: ..R RobotManager.setRobotOnline(LRobot;Z)V, RobotManager@287
```

```
1: .....X RobotManager.sendSequence(LRobot;..), RobotManager@287
```

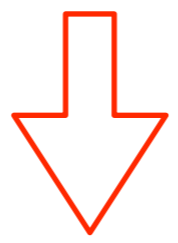
Example 5: Multithreaded GUI (5)



- ◆ better approach - precise properties from annotations (user docu)
- ◆ self explaining error message (no need for further analysis)
- ◆ much more efficient to check

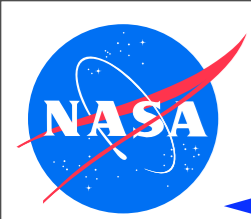
```
// means: RobotManager instances are not thread-safe, don't use them concurrently
@NonShared
public class RobotManager {
    ...

    ...
===== error #1
gov.nasa.jpf.jvm.NoUncaughtExceptionsProperty
java.lang.AssertionError: NonShared object: RobotManager@287
    accessed in live thread cycle: AWT-EventQueue-0,Thread-1,AWT-EventQueue-0,main
    at RobotManager$ListModel.getSize(RobotManager.java:170)
    ...
===== statistics
elapsed time:          0:00:01
states:               new=76, visited=0, backtracked=0, end=0
search:               maxDepth=75, constraints=0
choice generators:    thread=67, data=9
heap:                 gc=94, new=2668, free=212
instructions:         72884
    ...
```



```
elapsed time:          0:00:01
states:               new=76, visited=0, backtracked=0, end=0
search:               maxDepth=75, constraints=0
choice generators:    thread=67, data=9
heap:                 gc=94, new=2668, free=212
instructions:         72884
```

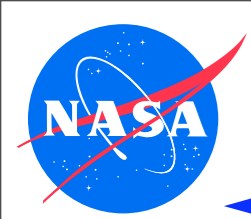
self-explaining,
doesn't even need
trace



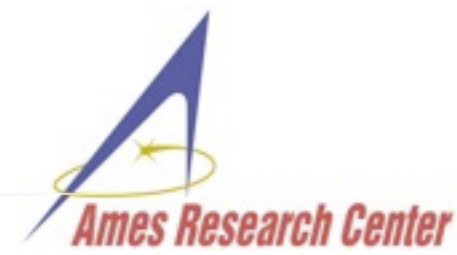
Examples: Deep Inspection



- ◆ focus is primarily on properties that require or benefit from VM level evaluation (execution history and details)
- ◆ checks do not modify SUT behavior (performed at VM level)
- ◆ orthogonal to path exploration (makes model checking more useful)
- ◆ can be based on “hints” (annotations) in SUT (JPF-aware application)
- ◆ can be just based on binary code (JPF unaware application)



Example 6: Const Annotation



- ◆ transitive properties (holds for certain dynamic scope)
- ◆ checked by dedicated listeners (runtime monitoring)
- ◆ does not require extensive annotation (const/var/unknown) of static analysis tools to avoid false positives

```
import gov.nasa.jpfc.annotation.Const;
```

```
public class ConstViolation {
    int d;
```

@Const

```
public void dontDoThis() {
    foo();
}
```

```
void foo () {
    d = 42;
}
```

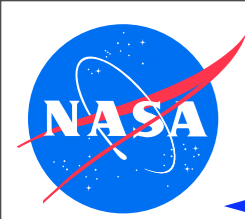
...

```
listener.autoload=gov.nasa.jpfc.annotation.Const,...
listener.gov.nasa.jpfc.annotation.Const=
    .aprop.listener.ConstChecker
```



=====
===== error #1

```
gov.nasa.jpfc.jvm.NoUncaughtExceptionsProperty
java.lang.AssertionError: instance field write within const context: int ConstViolation.d
    at ConstViolation.foo(ConstViolation.java:15)
    at ConstViolation.dontDoThis(ConstViolation.java:11)
    ...
```



Example 7: SandBox Annotation



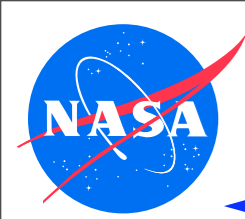
- ◆ more sophisticated, instance aware scope property
- ◆ instances only allowed to write “owned” fields (incl. fields of objects stored in reference fields)
- ◆ mechanism suitable for security related properties

```
class X {
    int d;
    void doSomethingUnsuspcious () {
        d++; // nothing bad in and of itself
    }
    ...
    @SandBox
    class Y {
        X myOwnX = ...
        void foo (X x){
            x.doSomethingUnsuspcious();
        }
        void bar () { myOwnX.d = 42; }
    }
    ...
    Y y = new Y();
    y.bar(); // fine
    y.foo(new X()); // not so fine
```

listener=.aprop.listener.ConstChecker



```
==== error #1
gov.nasa.jpj.jvm.NoUncaughtExceptionsProperty
java.lang.AssertionError: write to non-owned object: SandBoxViolation$X@290
                        from sandbox: SandBoxViolation$Y@294
    at SandBoxViolation$X.doSomethingUnsuspcious(SandBoxViolation.java:30)
    at SandBoxViolation$Y.foo(SandBoxViolation.java:37
```



Example 8: Programming-by-Contract



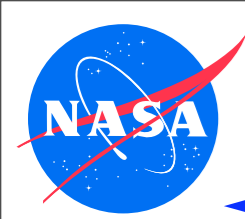
- ◆ property annotations can be parameterized with expressions
- ◆ can be a lot more complex
- ◆ inheritance aware
- ◆ expr evaluation has no SUT side-effects

```
class Base {
    @Ensures("Result > 0")
    public int compute (int c){ return c -1; }
    ...
    @Invariant({ "d within 40 +- 5", "a > 0" })
    public class Derived extends Base {
        double d; int a; // not checked until return from ctor

        ContractViolation() { a = 42; d = 42; }

        @Requires("c > 0")
        @Ensures("Result >= 0")
        public int compute (int c){
            return c - 3;
        }

        public void doSomething (int n){
            for (int i=0; i<n; i++){
                d += 1.0;
            }
        }
        ...
        Derived t = new Derived();
        //int n = t.compute(3); // would violate strengthening
                                base postcondition
        t.doSomething(10); // violates 'd' invariant
    }
}
```



Example 9: Overflow



- ◆ Java does not throw exceptions on overflow
- ◆ tedious to check in SUT \Rightarrow usually ignored

JPF configuration

```
vm.insn_factory.class =
    .numeric.NumericInstructionFactory
```

```
...
2103933699
2123371282
2142808865
```

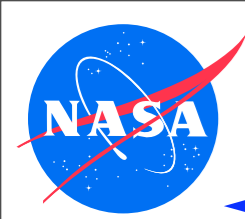
```
...
===== error #1
gov.nasa.jpf.jvm.NoUncaughtExceptionsProperty
java.lang.ArithmeticException: integer overflow: 2142808865+19437583 = -2132720848
    at Overflow.notSoObvious(Overflow.java:18)
...

```

System
under Test
Report

```
void notSoObvious(int x){
    int a = x*50;
    int b = 19437583;
    int c = a;

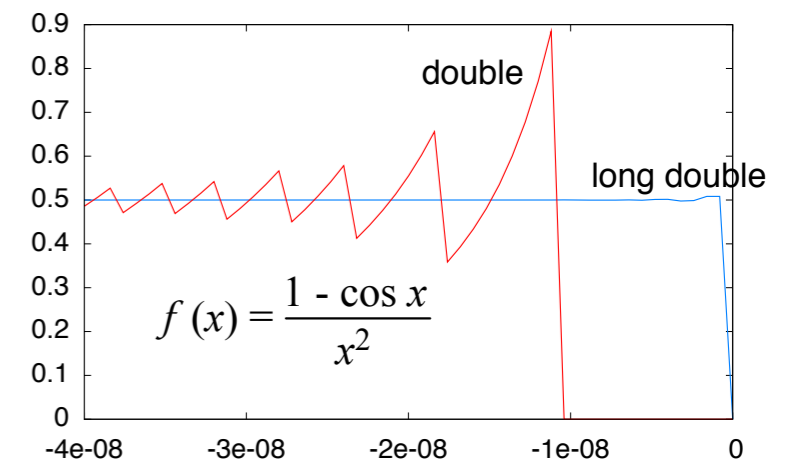
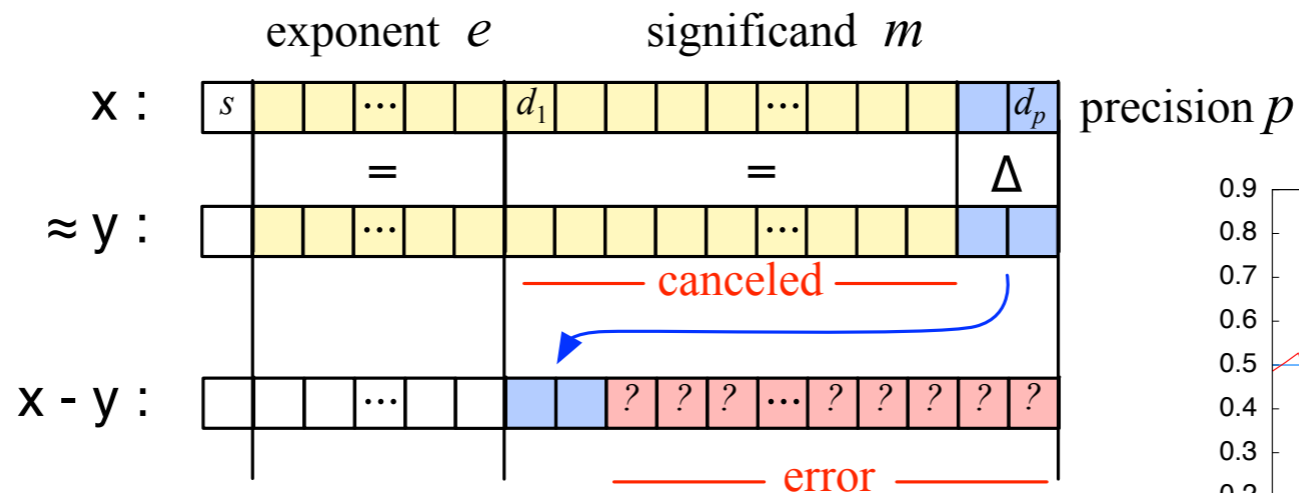
    for (int k=0; k<100; k++){
        c += b;
        System.out.println(c);
    }
}
...
notSoObvious( 21474836);
```



Example 10: Catastrophic Cancellation



- ◆ errors and required inspection can be a lot more intricate
- ◆ e.g.: amplification of previous operand errors due to cancellation of identical leading bits in the significands, followed by normalization of the result

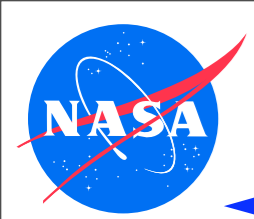


```
double a = 77617.0;
double b = 33096.0;
res = 333.75*pow(b,6) + pow(a,2)*(11*pow(a,2)*pow(b,2) -
pow(b,6) - 121*pow(b,4) - 2) + 5.5*pow(b,8) + a/(2*b);
```



```
vm.insn_factory.class =
    .numeric.NumericInstructionFactory
```

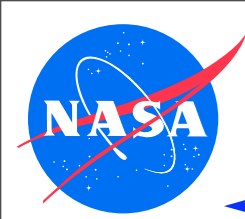
```
res=-1.1805916207174113e21 (should be -0.827396...)
...
===== error #1
gov.nasa.jpj.jvm.NoUncaughtExceptionsProperty
    java.lang.ArithmeticException: cancellation of:
        -7.917111340668963E36 + 7.917111340668962E36
        = -1.1805916207174113E21
```



Examples: Model Verification



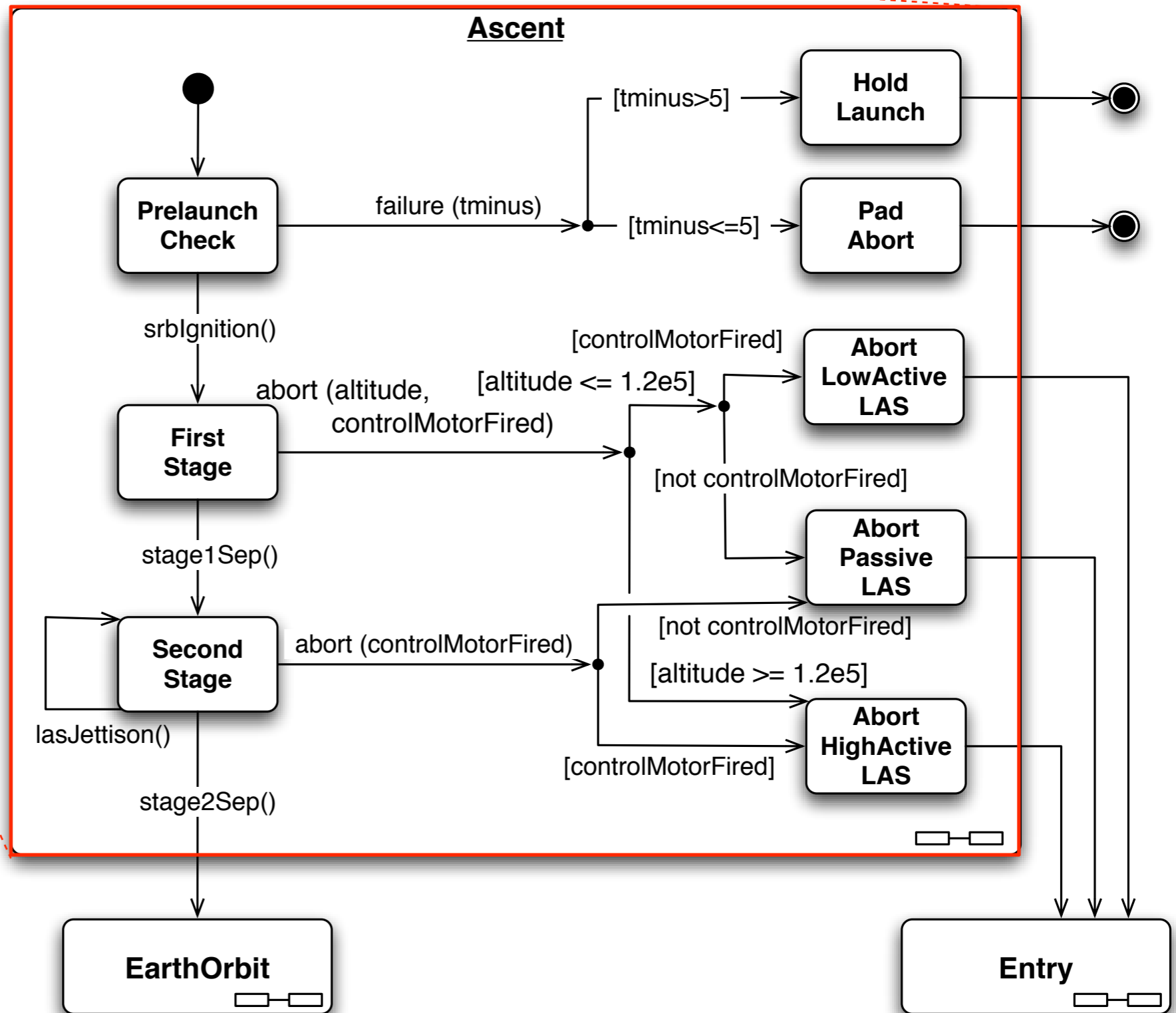
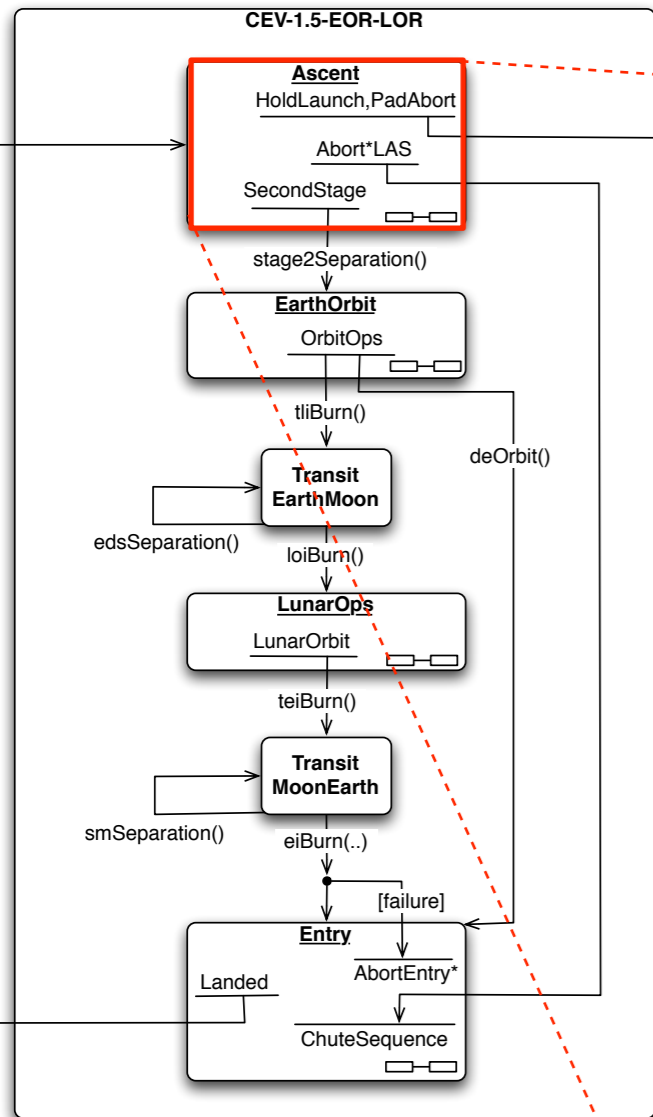
- ◆ motivation: model driven development
- ◆ as models get more complex, risk of model inconsistencies increases
- ◆ classic example: state machine verification
- ◆ usually requires translation into JPF specific model representation (application that is JPF dependent)



UML Model Checking (1)



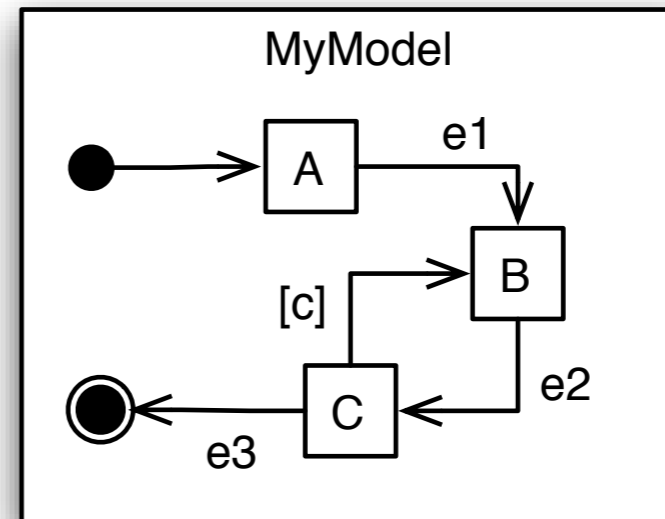
model is understandable ..



.. but does it work?
(actions, guards,
reachability etc.)

- ◆ to find out:
 - make model executable (give it formal semantics) ⇒ translation
 - execute it with JPF (systematically checking all enabling events and parameter combinations)

UML Statechart

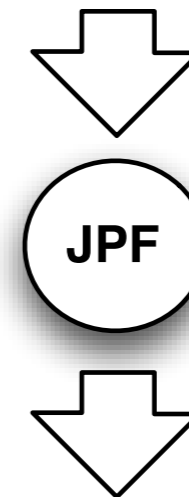


Java Program

```

class MyModel extends State {
    class A extends State {...}
    class B extends State {...}
    class C extends State {...}
}
    
```

Software Model Checker



[guidance script]

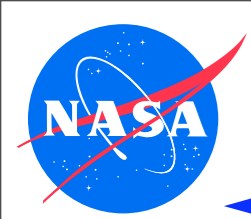
```

..
e1()
e2()
ANY{*}
    
```

Verification Report

```

error:
    unreachable end state...
trace:
    e1(), e2() ...
    
```

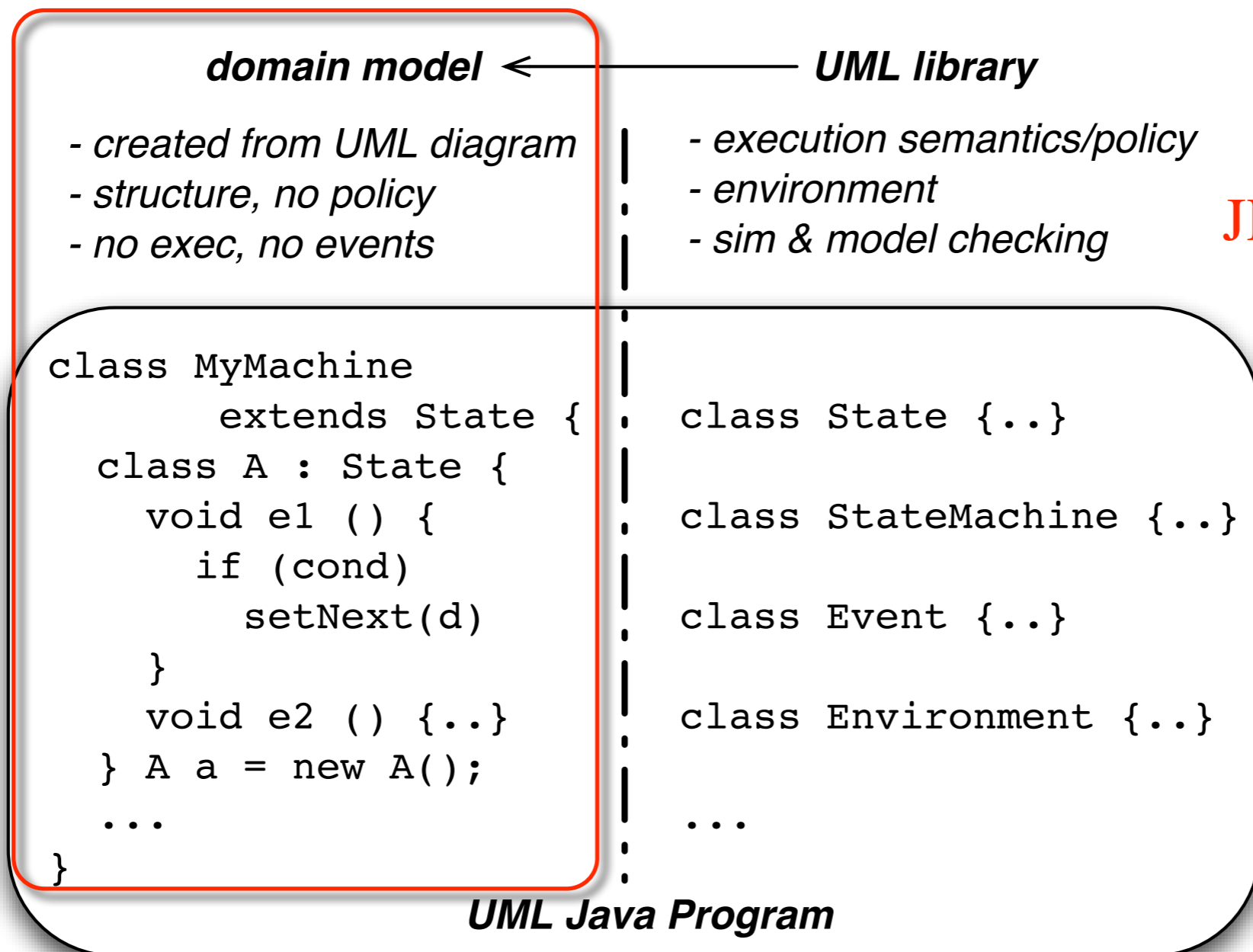


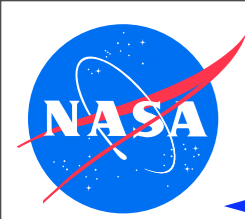
UML Model Checking (3)



- ◆ layer 1: domain model (code translated from UML diagram)
- ◆ layer 2: UML modeling library (part of JPF distribution)
- ◆ goals: model readability, UML/program state space alignment

translated





Example 11: UML Model Checking

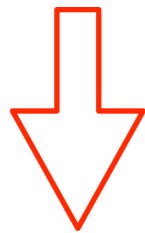


◆ property: “no unhandled exceptions”

```

class OrbitOps {..
  void lsamRendezvous(){..
    assert !spacecraft contains(LAS):
      "lsamRendezvous with LAS attached"
    ..
  } ..
}

```



```

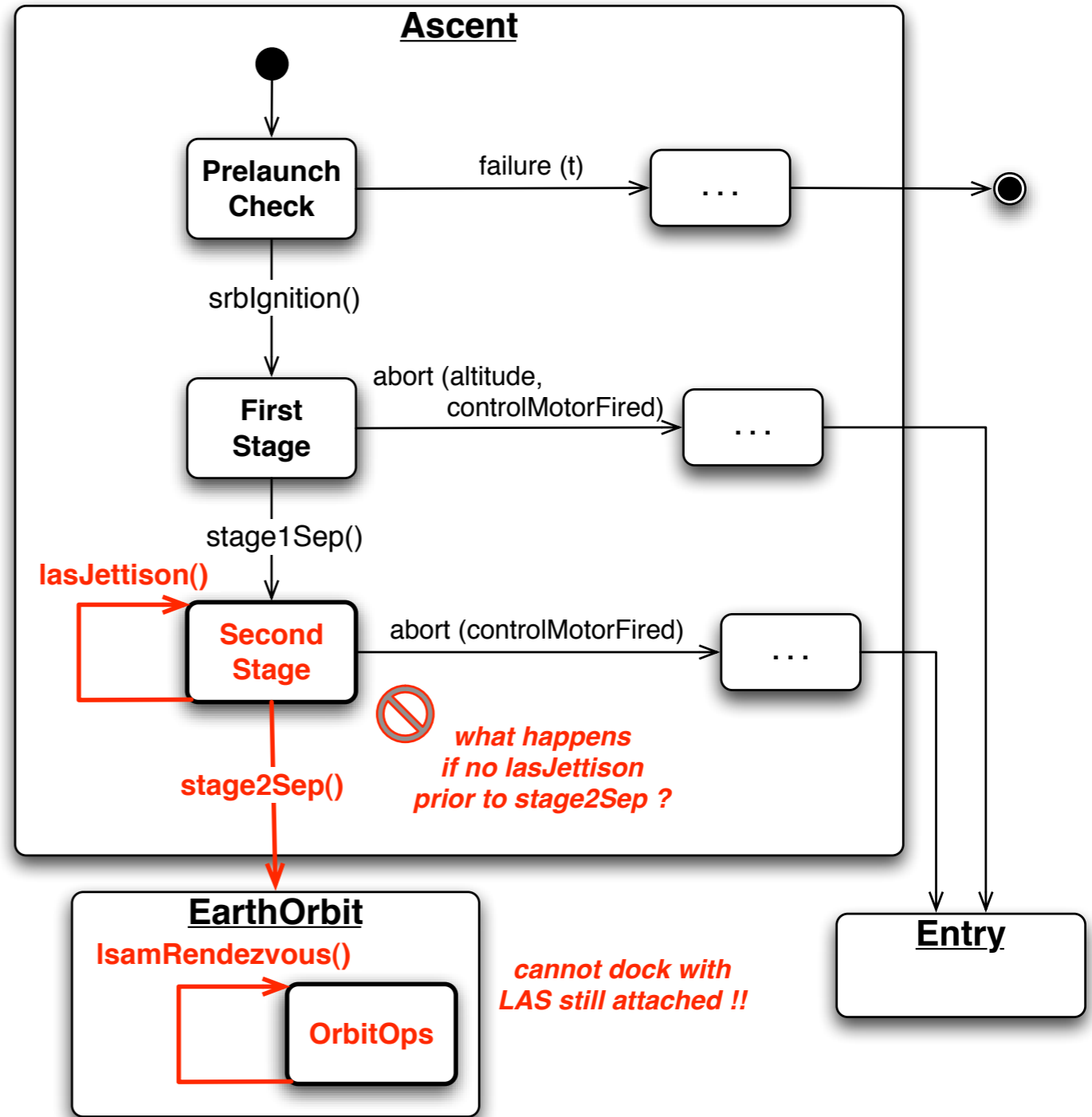
...
===== error #1
NoUncaughtExceptionsProperty
AssertionError:
  lsamRendezvous with LAS attached
  at ...

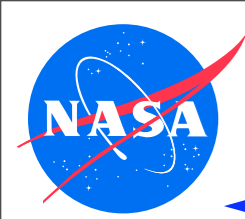
```

```

===== choice trace #1
srbIgnition()
stage1Separation()
stage2Separation()
lsamRendezvous()

```





Example 12: UML Model Checking



◆ property: “all states of the model have to be reachable”

```
class EarthOrbit {..
  void entry_checkSensors() {..
    if (!checkEarthSensor()) earthSensorFailed = true;
```

autom. entry action

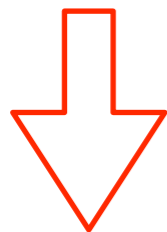
```
class Insertion {..
  void entry_setMajorMode() {..resetSensors();..}
```

```
void resetSensors() {..
  earthSensorFailed = false; }
```

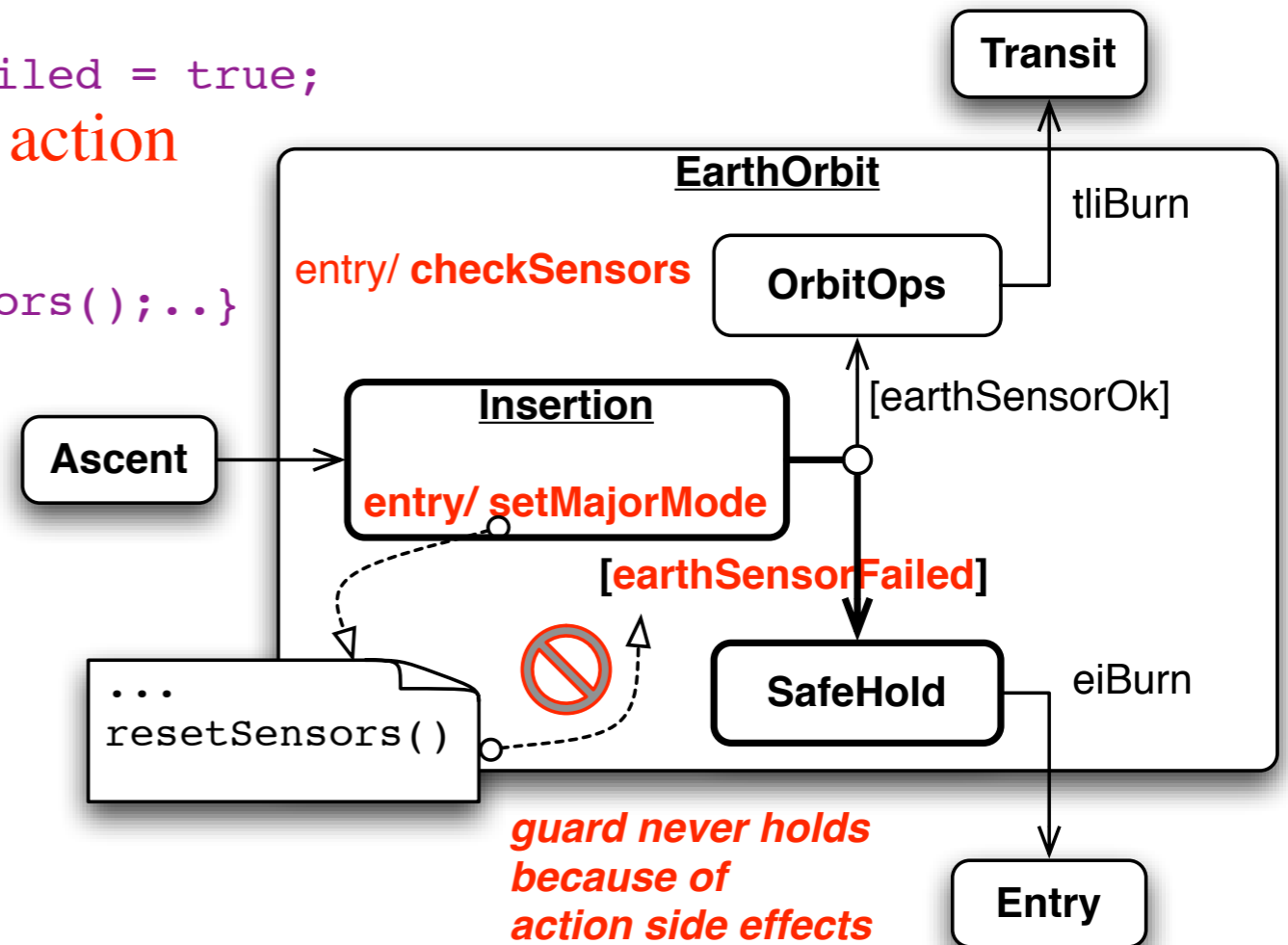
```
void completion() {
  if (earthSensorFailed)
    setNextState(safeHold);
  ..
}
```

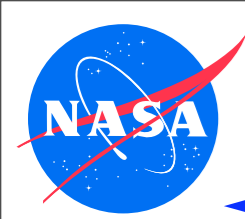
never holds

```
listener=.tools.sc.Coverage
sc.required=earthOrbit
```



```
...
===== error #1
gov.nasa.jpfc.tools.sc.Coverage
required earthOrbit.safeHold NOT COVERED
...
```





Example 13: UML Model Checking



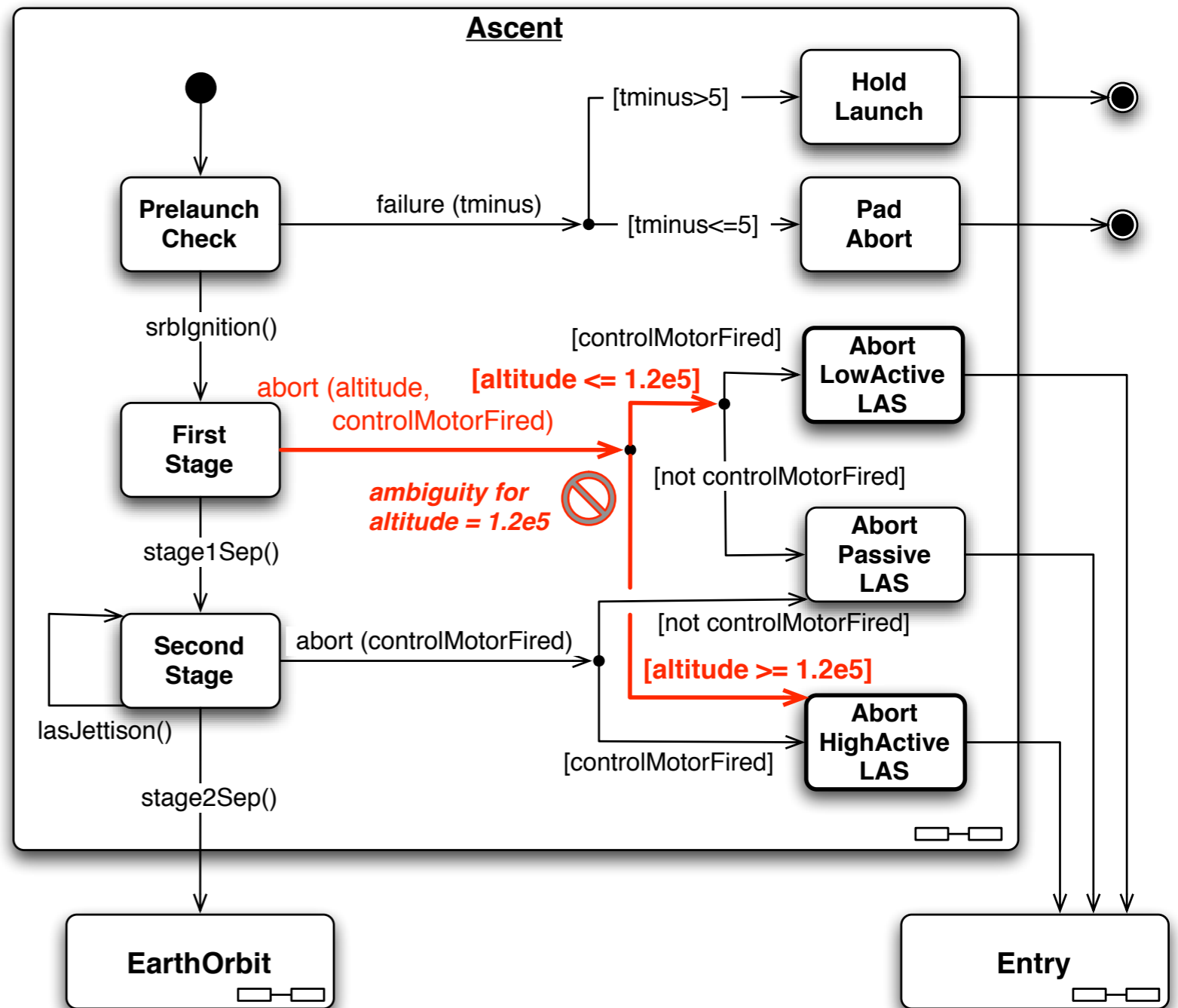
- ◆ property: “no ambiguous transitions”
- ◆ example: overlapping guard conditions

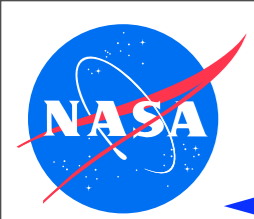
```
@Params("5000|120000|200000,..")
void abort(altitude,..){..
  if (altitude <= 1.2e5)
    setNextState(abortLowActive)
  ...
  if (altitude >= 1.2e5)
    setNextState(abortHighActive)
}
```



```
==== error #1 ...
AssertionError:
ambiguous transitions in:
    ascent.firstStage
processing event: abort(120000,true)
state 1: ascent.abortHighActiveLAS
state 2: ascent.abortLowActiveLAS
...
```

```
==== choice trace #1
srbIgnition()
abort(120000,true)
```

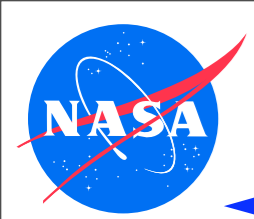




Examples: Test Case Generation



- ◆ test creation is very expensive - how many tests do we need (instruction coverage, branch coverage, MCDC, path coverage ..)
- ◆ the application for *symbolic execution*
- ◆ “normal” verification - use data to find out which paths to explore
- ◆ problem with huge input spaces (what test data is interesting?)
- ◆ symbolic execution uses opposite direction - use program structure to deduce which data values need to be tested to reach interesting program locations (exceptions, coverage requirements)



Test Case Generation (1)

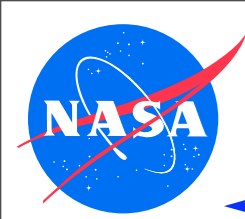


- ◆ how do we identify interesting parameter values if they are not known a priori (example 13 @PARAMS annotation)?

```
@PARAMS(5000|120000|200000)
```

```
void abort(altitude){  
    ...  
    if (altitude <= 1.2e5)  
        setNextState(abortLowActive)  
    ...  
    if (altitude >= 1.2e5)  
        setNextState(abortHighActive)
```

- ◆ answer: test case generation with *Symbolic Execution*



Test Case Generation (2)



Program Control Structure

```

if (x > C) {
  ...
  if (y < D) {
    ...
    ...
    if (x >= y) {
      ...
    } else {
      ...
    }
  }
  ...
}

```

Path Conditions

PC₁: (x > C)

PC₂: (y < D)

⋮

PC_n: ¬(x ≥ y)

Symbolic Execution

? how do we get here ?

$$PC_1 \wedge PC_2 \wedge \dots \wedge PC_n = \text{true}$$

constraint solver

[x=..., y=..]

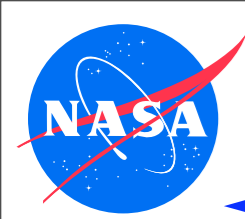
∅

?

concrete test vector(s)

unreachable code

program logic too complex ?



Example 14: Symbolic Execution



- ◆ look for instruction that constitutes property violation and compute data that leads to it

```
vm.insn_factory.class =
  gov.nasa.jpf.symbc.SymbolicInstructionFactory
symbolic.method = ..abort(sym#con)
...
```

```
symbolic.dp=choco
Symbolic Execution Mode
```

```
...
***Execute symbolic INVOKEVIRTUAL: abort(IZ)V
      (altitude_1_SYMINT, controlMotorFired_CONCRETE )
```

```
...
Property Violated: PC is # = 2
altitude_1_SYMINT[120000] >= CONST_120000 &&
altitude_1_SYMINT[120000] <= CONST_120000
```

```
...
Property Violated: result is "java.lang.AssertionError: ambiguous transitions
in: ascent.firstStage..."
```

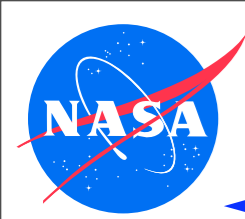
```
=====  
Method Summaries
```

```
Symbolic values: altitude_1_SYMINT
```

```
abort(120000,true) --> "java.lang.AssertionError: ambiguous transitions in:
ascent.firstStage..."
```

```
void abort(altitude,controlMotorFired){
  ...
  if (altitude <= 1.2e5)
    setNextState(abortLowActive)
  ...
  if (altitude >= 1.2e5)
    setNextState(abortHighActive)
```





Example 15: Test Case Generation



- ◆ Symbolic Execution especially suitable to generate test suite to achieve path coverage

```
vm.insn_factory.class =
    .symbc.SymbolicInstructionFactory
symbolic.method= TestPaths.testMe(sym#con)
listener = .symbc.SymbolicListener
```

```
public class TestPaths {
    ...
    // what tests do we need to cover all paths?
    public static void testMe (int x, boolean b) {
        if (x <= 1200){
            // BLOCK-1
        }
        if(x >= 1200){
            // BLOCK-2
        }
    }
}
```

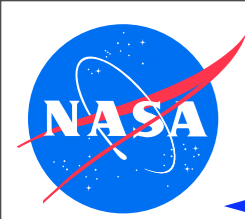


```
...
***Execute symbolic INVOKESTATIC: testMe(IZ)V ( x_1_SYMINT, b_CONCRETE )
```

```
..
PC # = 2
x_1_SYMINT[1200] >= CONST_1200 &&
x_1_SYMINT[1200] <= CONST_1200
...
x_1_SYMINT[-1000000] < CONST_1200 &&
x_1_SYMINT[-1000000] <= CONST_1200
...
```

=====
Method Summaries

```
...
testMe(1200,true)          BLOCK-1, BLOCK-2
testMe(-1000000,true)     BLOCK-1
testMe(1201,true)         BLOCK-2
```



Examples: Distributed Applications

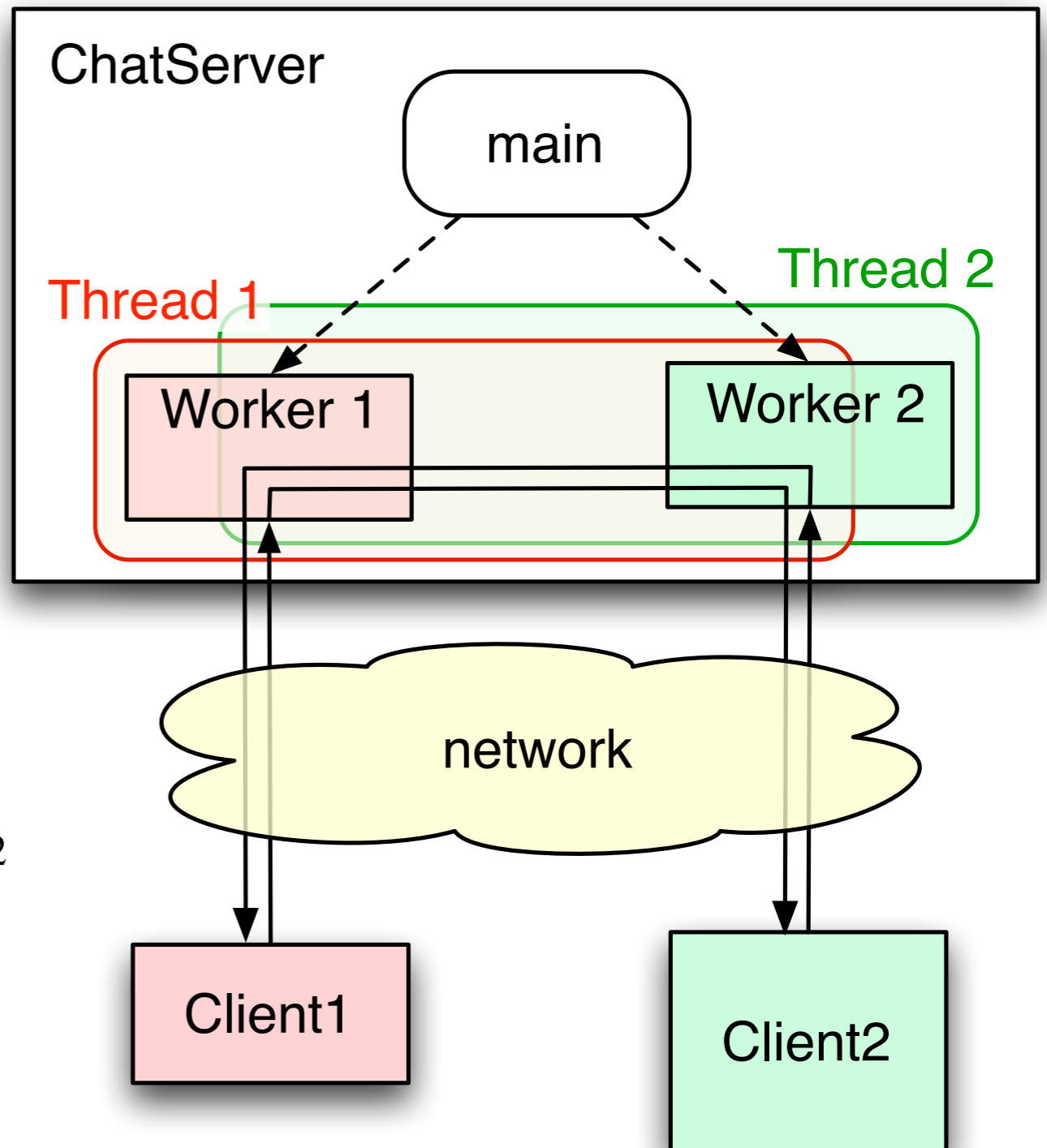


- ◆ example: ChatServer
- ◆ 1 ChatServer process
- ◆ N Client processes
- ◆ server creates one worker object/thread per connection

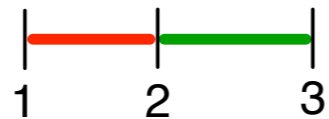
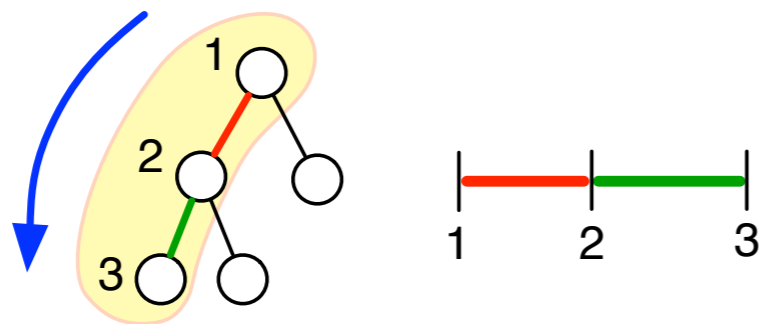
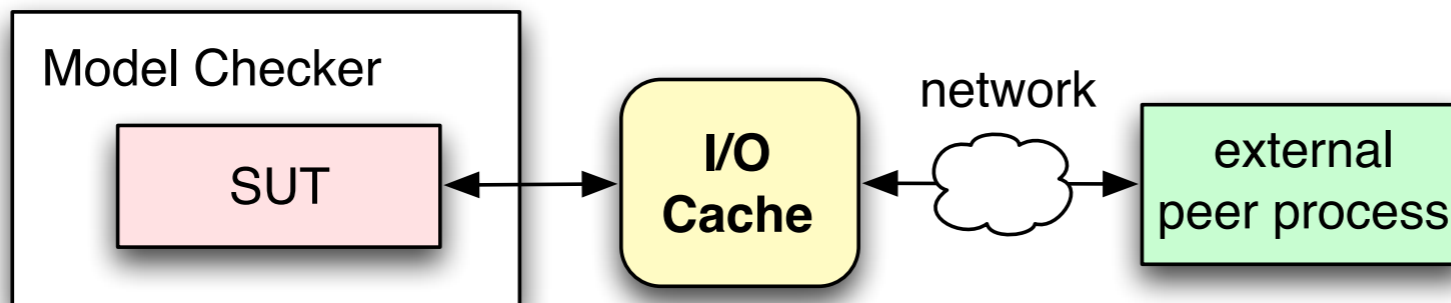
- ◆ model checking problem:
 - state explosion for known clients:

$$S_{\text{total}} = S_{\text{server}} \times S_{\text{client1}} \times S_{\text{client2}}$$

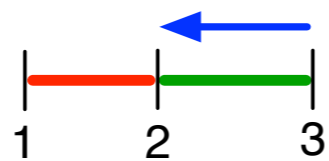
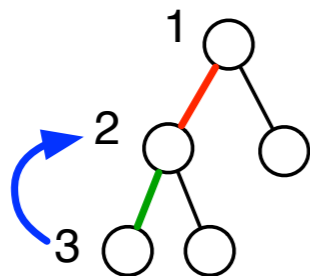
- what to do if clients unknown ?



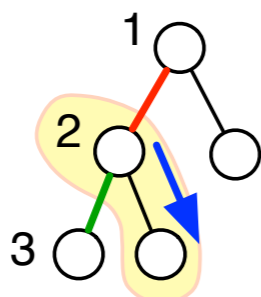
- ◆ no stubs required
- ◆ environment executes normally
- ◆ protocol structure preserved



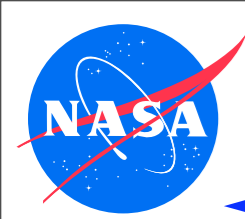
new state: store I/O data streams "globally"
 cache I/O data & message size
 map program state to stream position



backtracking: restore I/O state "locally"
 reset streams back to old state



continue: replay previous I/O
 duplicate sends: ignore
 duplicate reads: previous peer response



Example 16: ChatServer Deadlock



◆ jpf-net-iocache finds server defect (deadlock) without analyzing clients

```
listener=.network.listener.CacheNotifier,  
        .network.listener.CacheLogger
```

```
...  
[SEVERE] unprotected field access  
of ChatServer.workers  
in thread: Thread-1..
```

```
...  
Client quit, 1 client(s) left.  
Client quit, 1 client(s) left.
```

```
=====  
error #1
```

```
gov.nasa.jpf.jvm.NotDeadlockedProperty  
deadlock encountered:
```

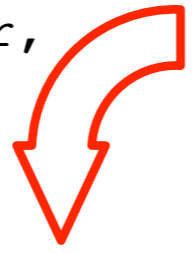
```
thread index=0,name=main,status=WAITING..  
thread index=1,name=Thread-0,status=TERMINATED..  
thread index=2,name=Thread-1,status=TERMINATED..
```

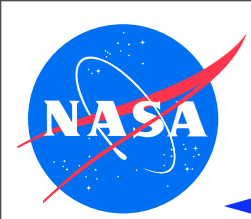
```
=====  
snapshot #1
```

```
thread index=0,name=main,status=WAITING...  
waiting on: gov.nasa.jpf.network.chat.ChatServer@294  
call stack:  
at gov.nasa.jpf.network.chat.ChatServer.accept(ChatServer.java:85)  
...
```

```
class Worker implements Runnable {  
...  
public void run() {  
    ..server.remove(id)  
...  
}
```

```
class ChatServer {  
...  
void remove(int n) {  
    workers[n] = null;  
    activeClients--;  
    synchronized (this){  
        notify();  
    }  
...  
void accept(int maxServ, int port) {  
...  
    synchronized (this) {  
        while (activeClients != 0) {  
            try {  
                wait();  
            }  
...  
}
```

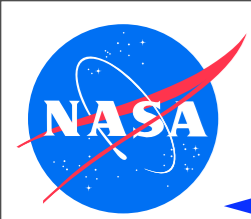




Using JPF



- ◆ obtaining JPF
- ◆ installing, building and testing JPF
- ◆ JPF configuration
- ◆ running JPF
- ◆ JPF and NetBeans
- ◆ JPF and Eclipse



Extending JPF

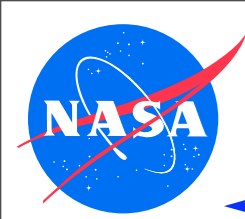


◆ Basics

- a VM running inside a JVM
- JPF Components
- JPF directory structure
- JPF runtime structure

◆ Extension Mechanisms

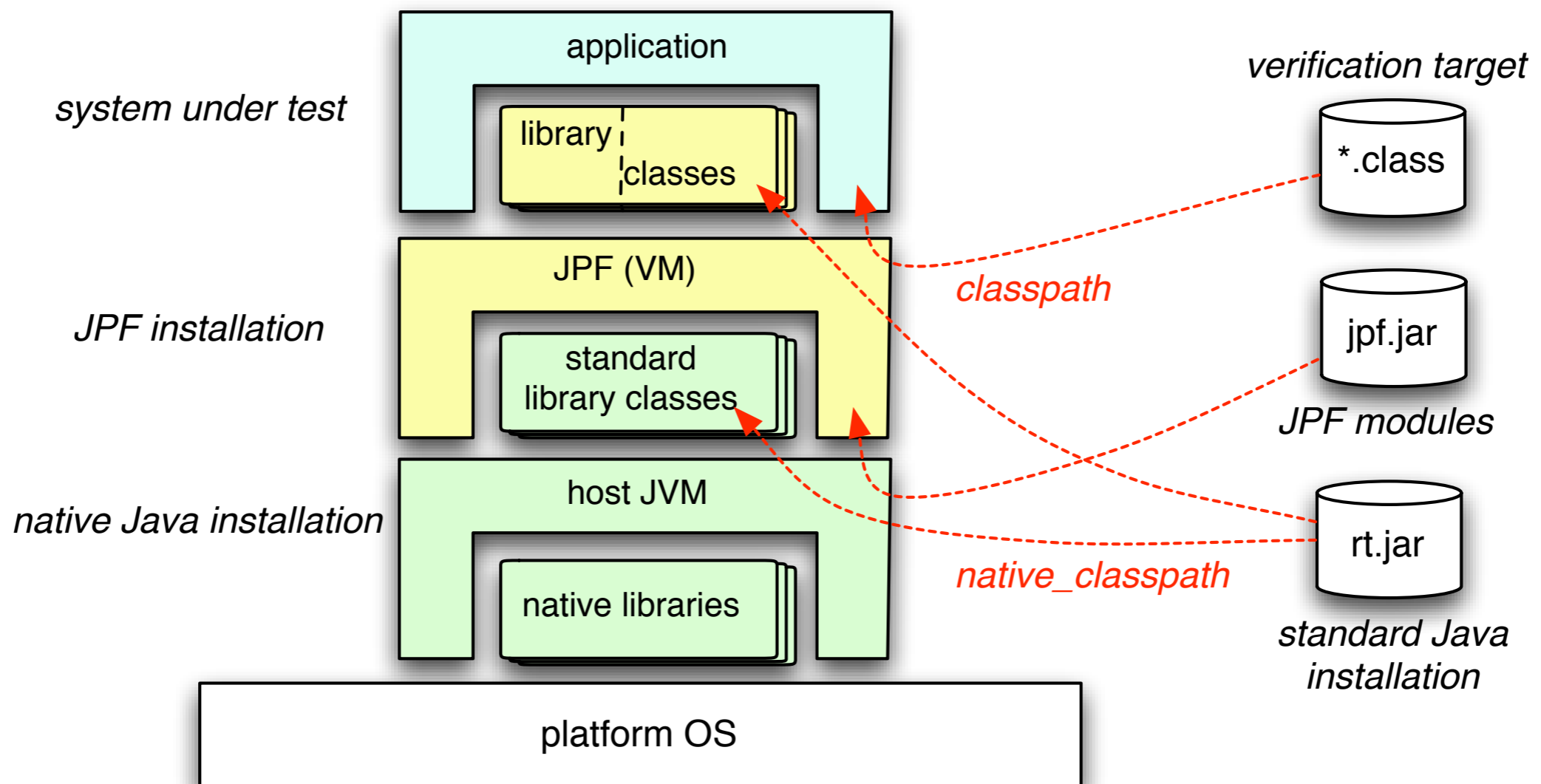
- Search Policies
- ChoiceGenerators
- Listeners
- Bytecode Factories
- Model-Java-Interface and Native Peers
- Attributes

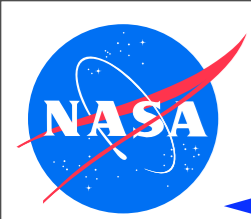


Basics: a VM running inside JVM



- verified Java program is executed by JPF, which is a virtual machine implemented in Java, i.e. runs on top of a host JVM
⇒ easy to get confused about who executes what





Conclusions



- ◆ check out <http://babelfish.arc.nasa.gov/trac/jpf>
- ◆ all answers will be there (eventually)
- ◆ .. if not - try <http://groups.google.com/group/java-pathfinder>
- ◆ if not - we are here to help: Peter.C.Mehlitz@nasa.gov